

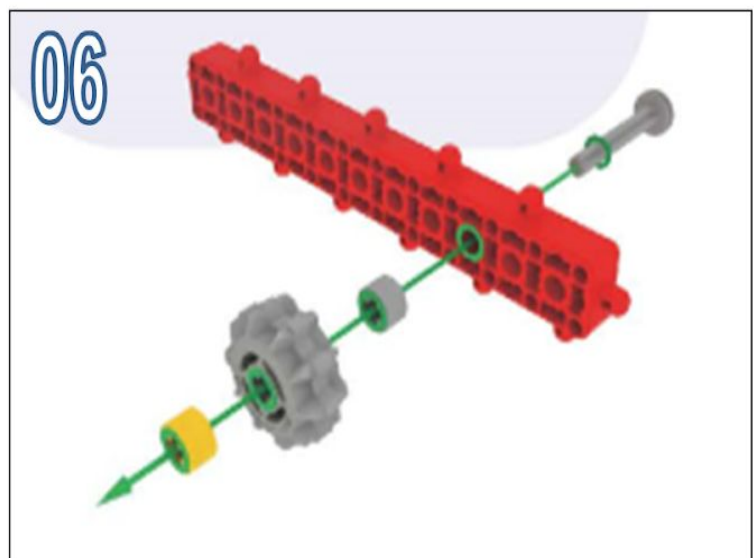
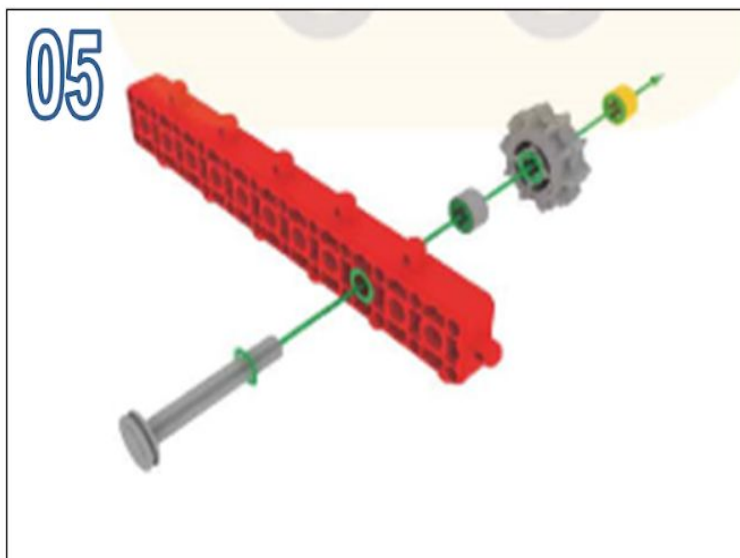
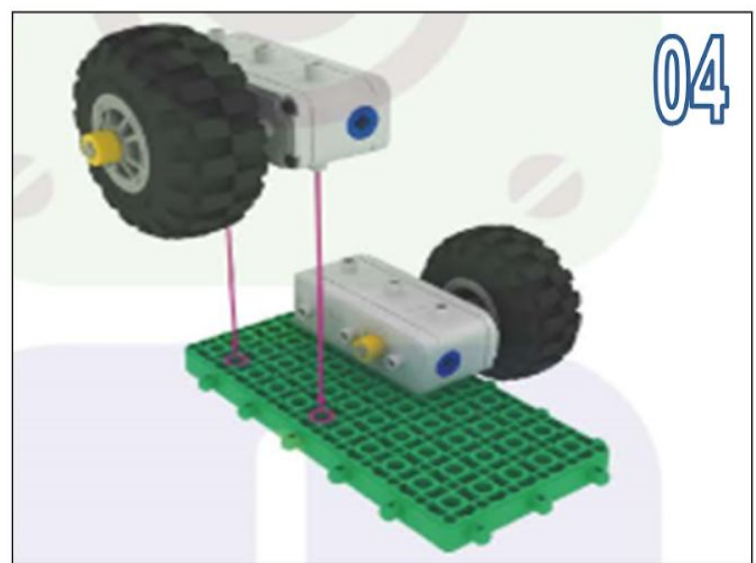
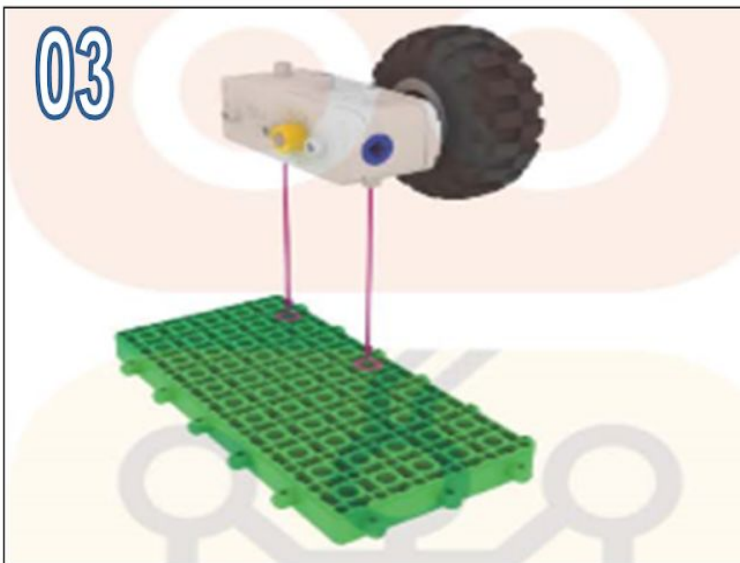
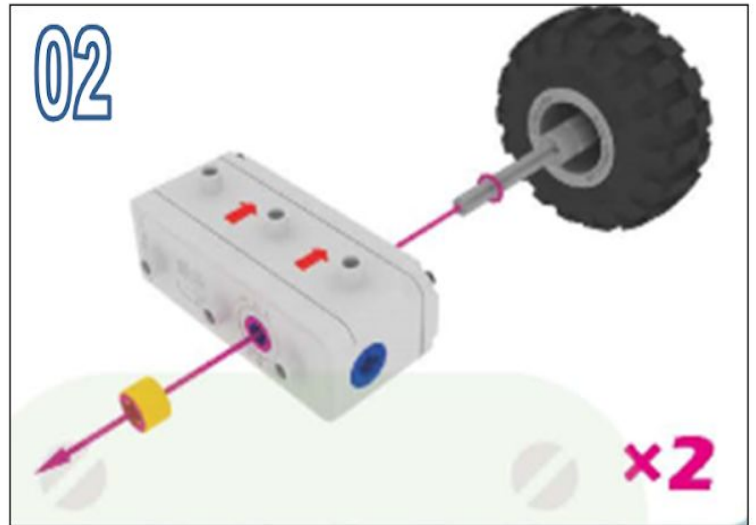
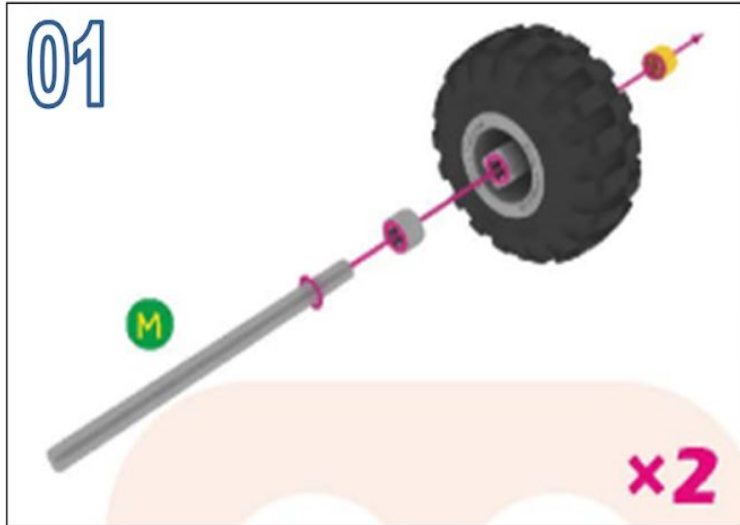


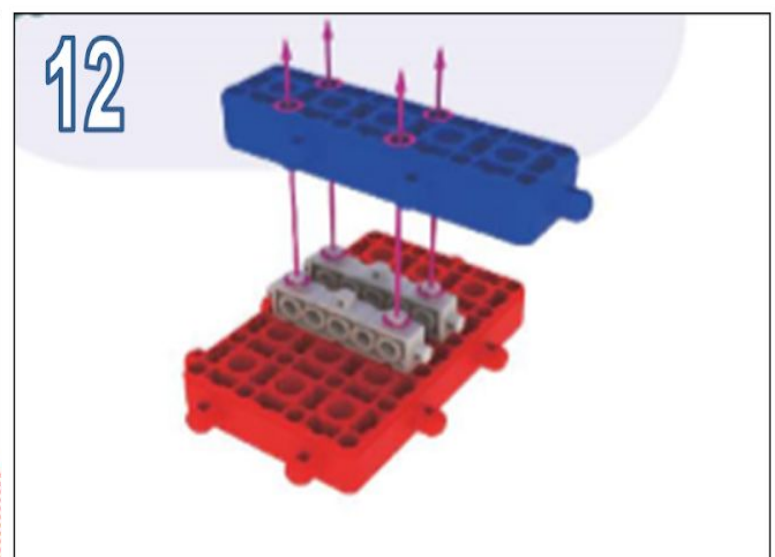
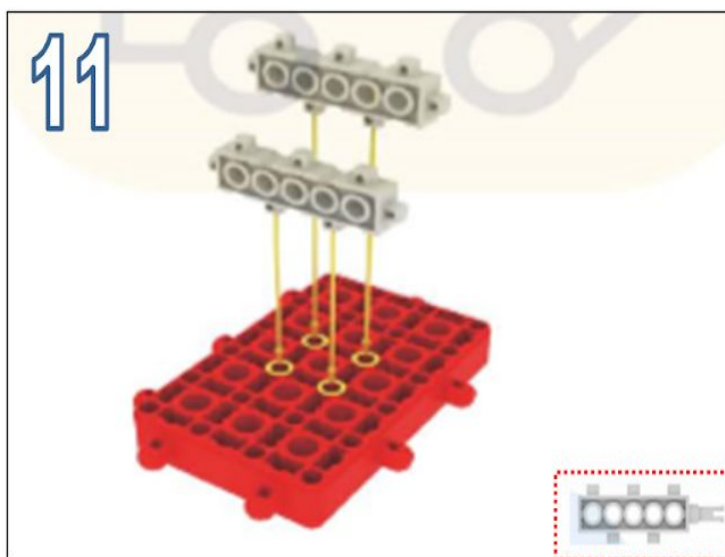
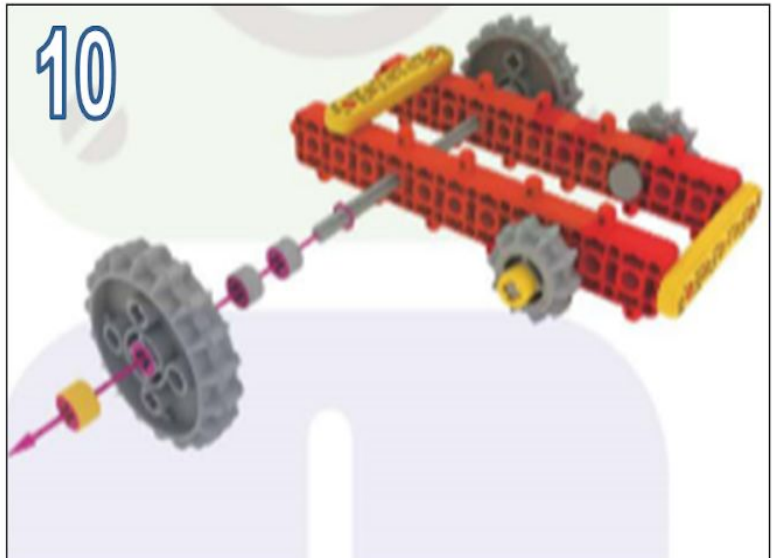
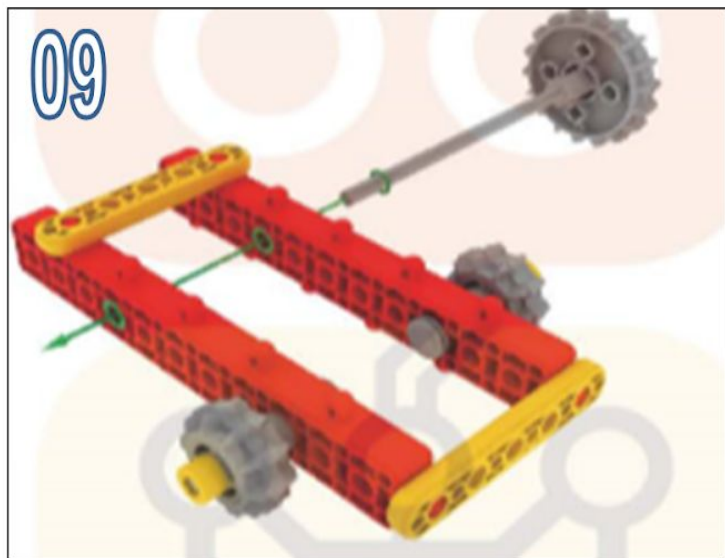
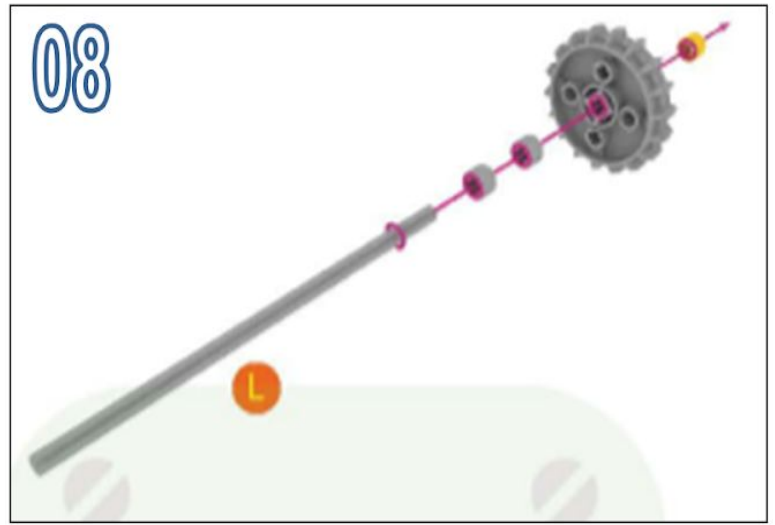
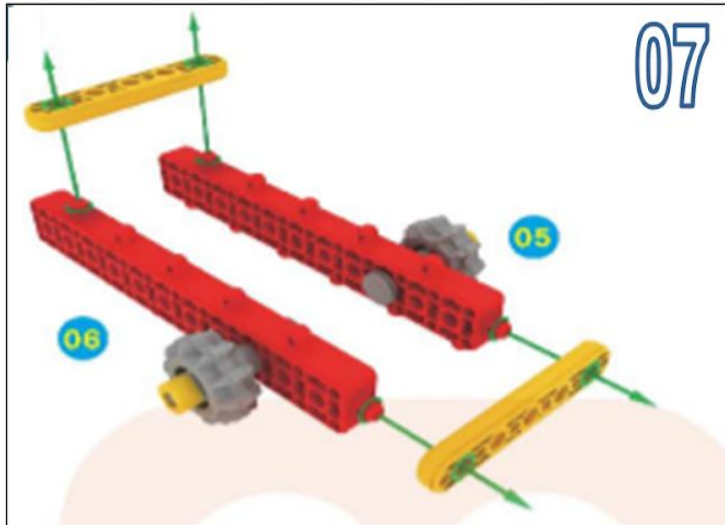
MY ROBOT TIME

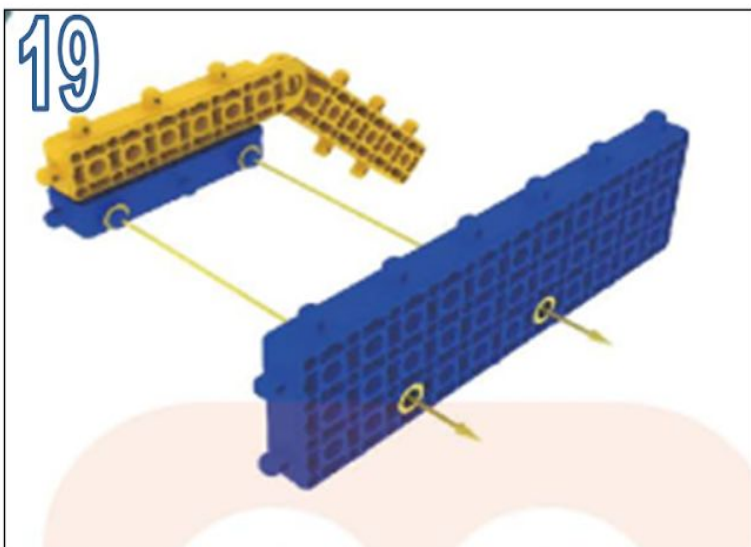
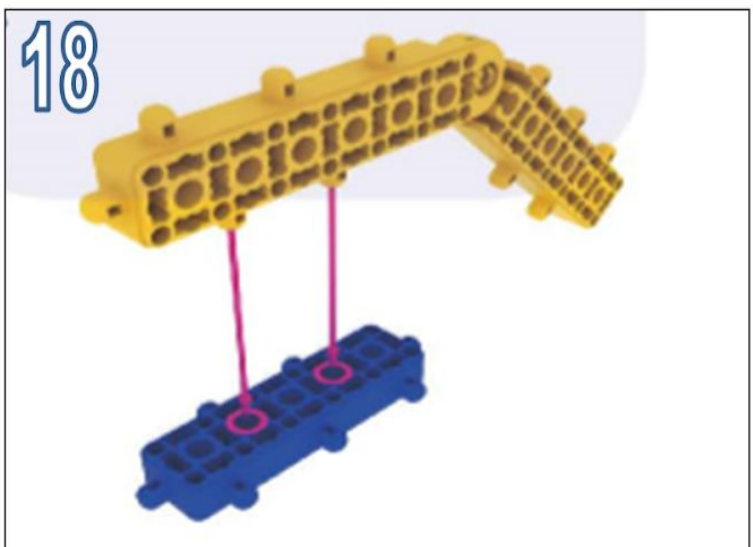
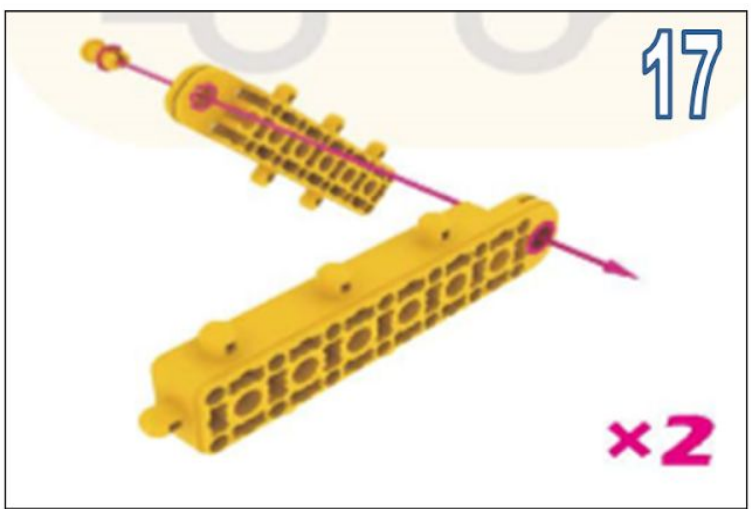
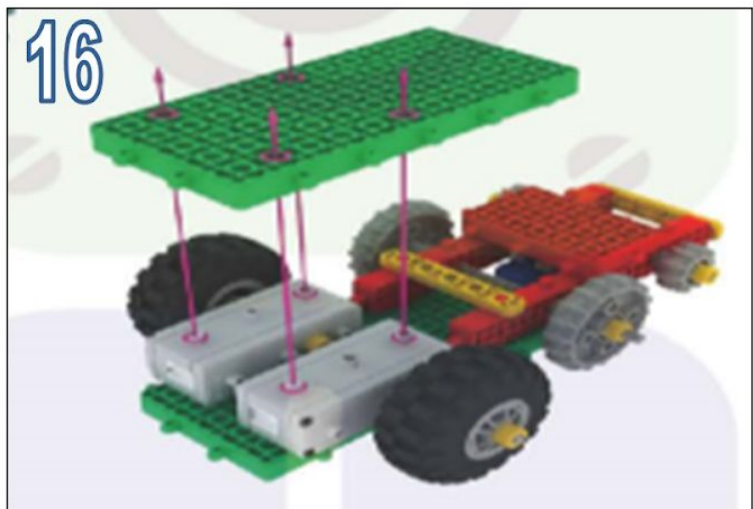
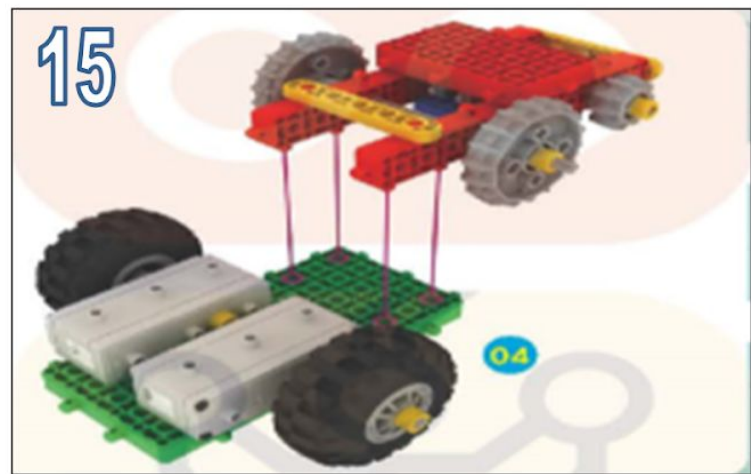
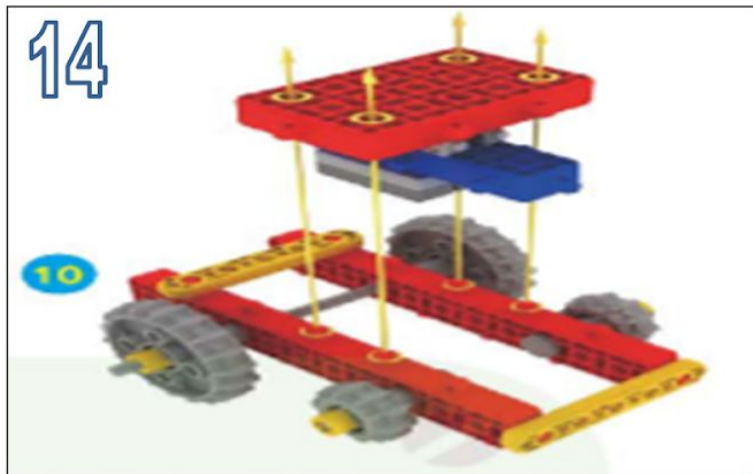
CONSTRUCCIÓN N° 3

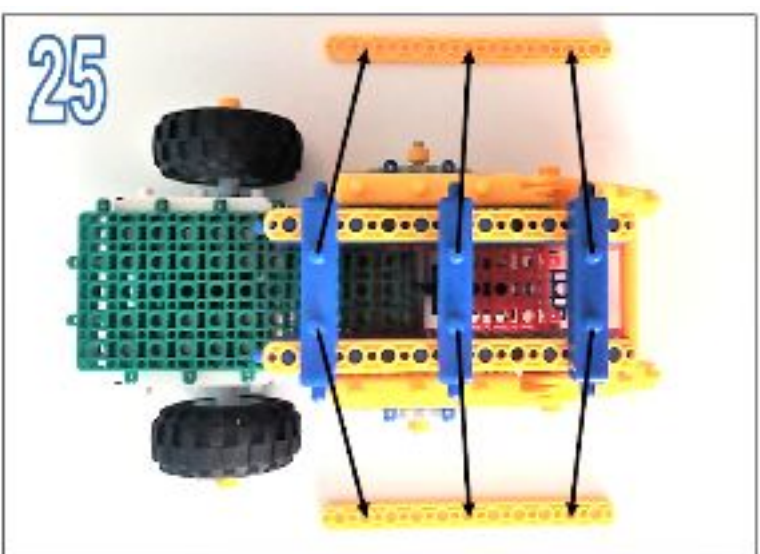
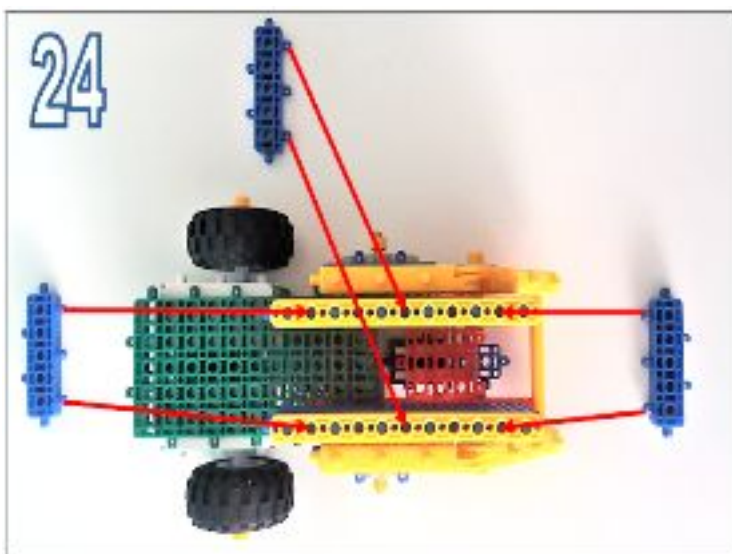
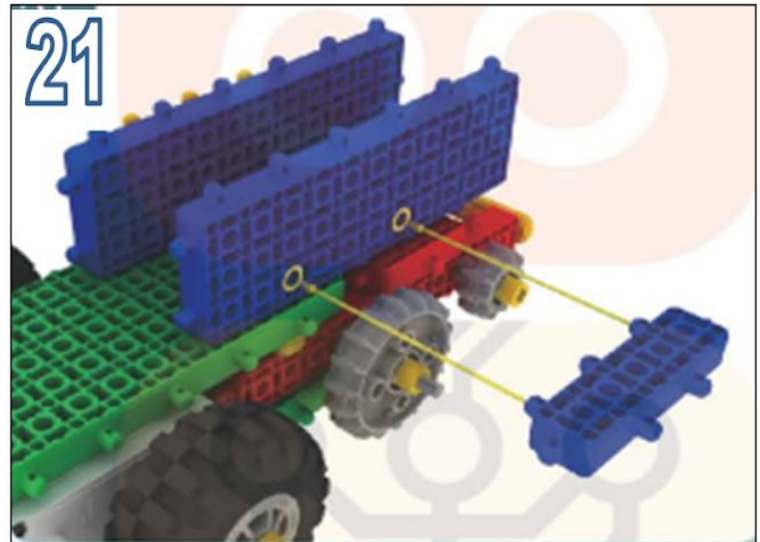
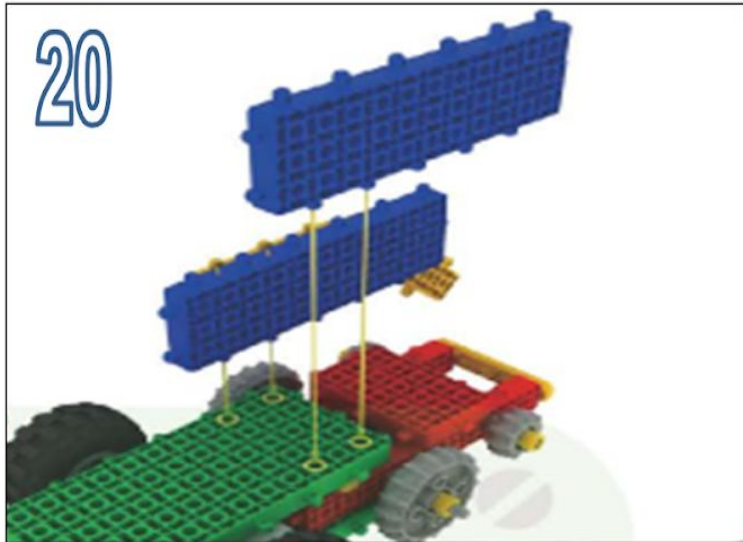
Tren robótico

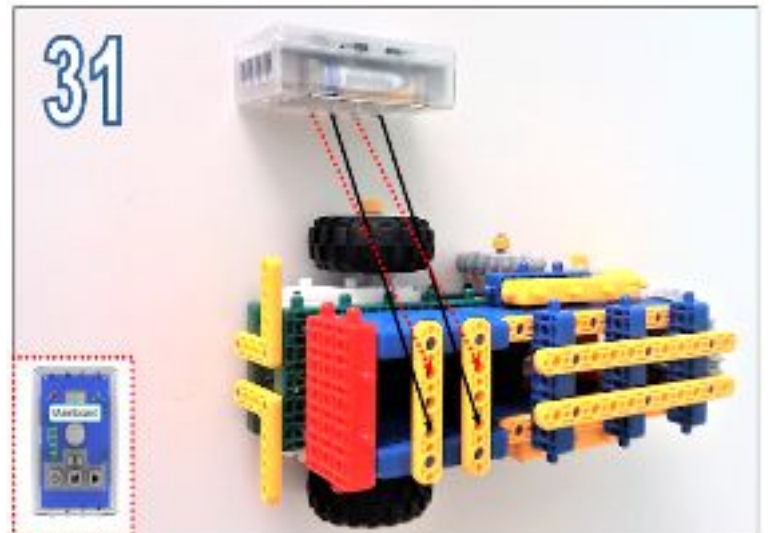
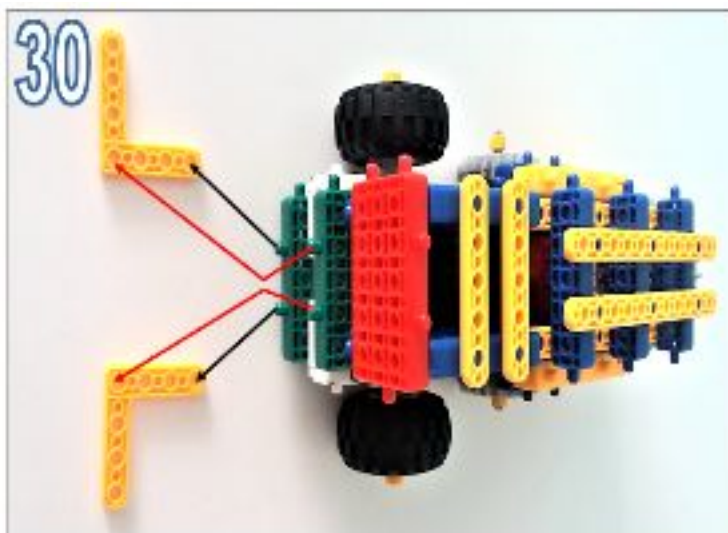
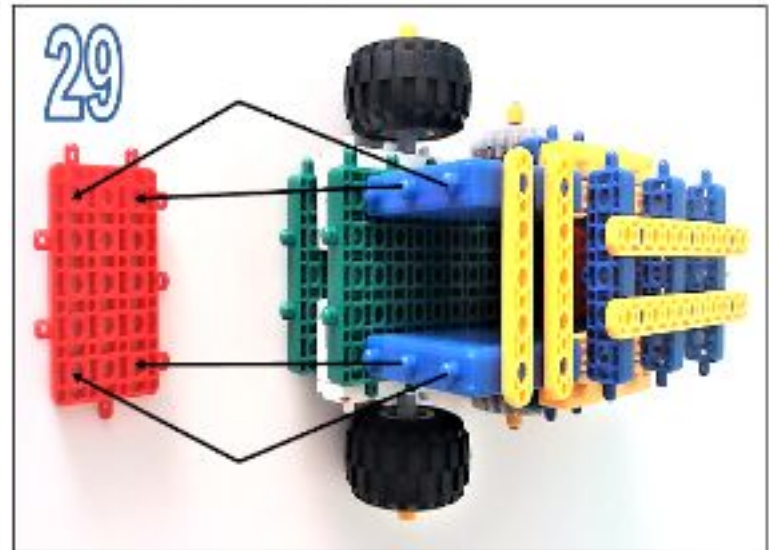
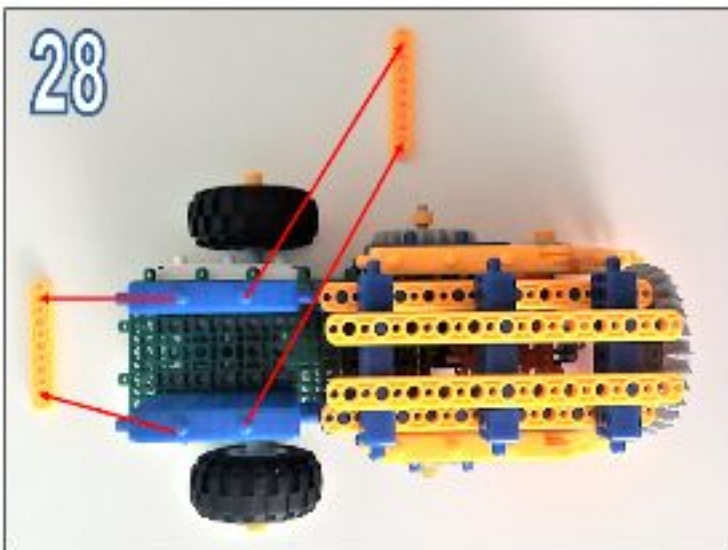
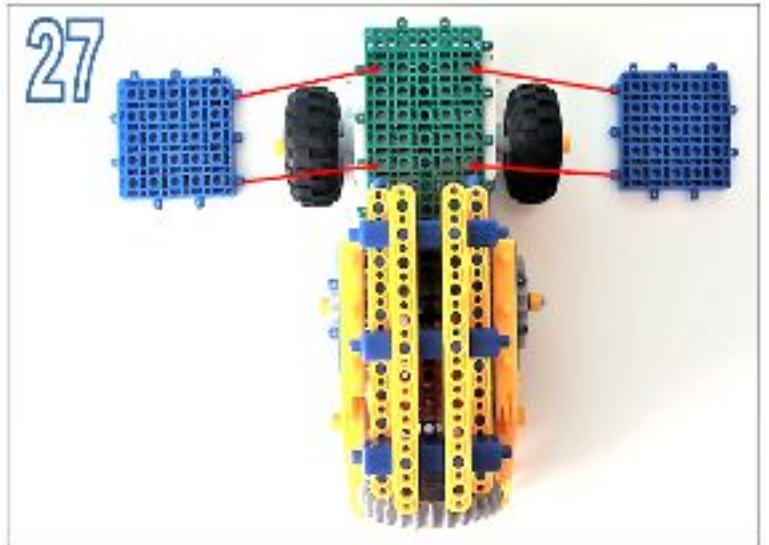
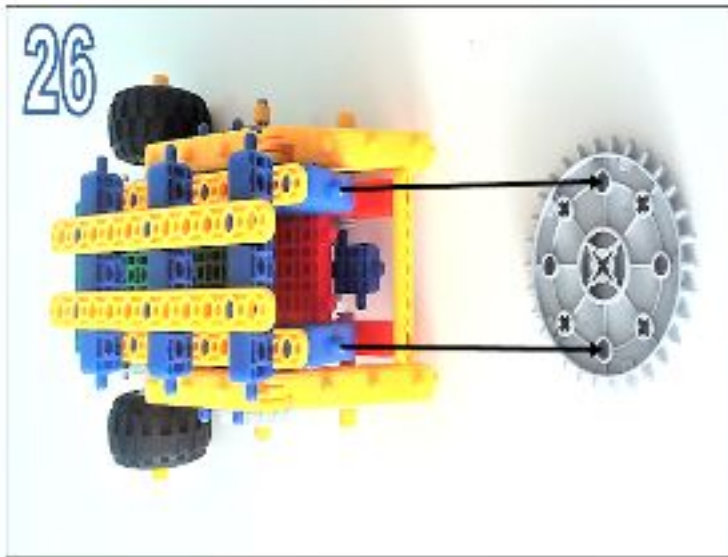


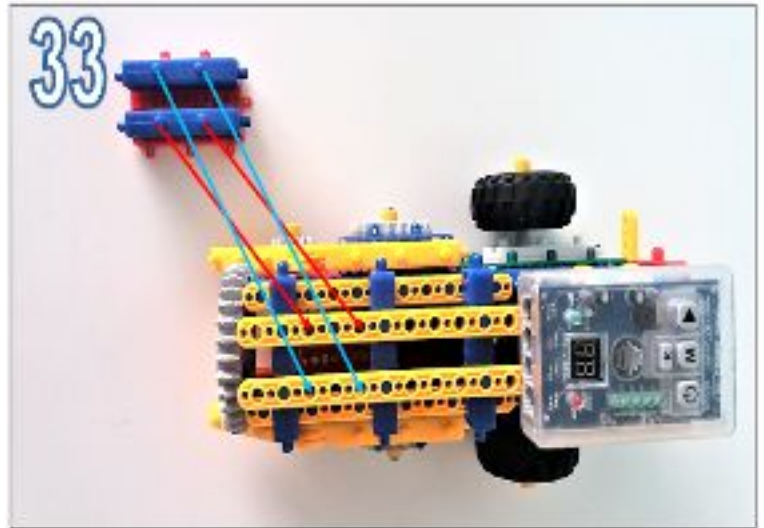
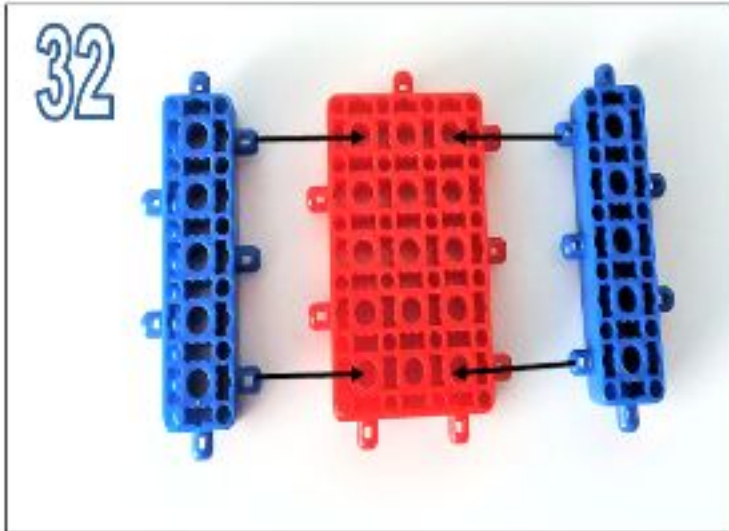




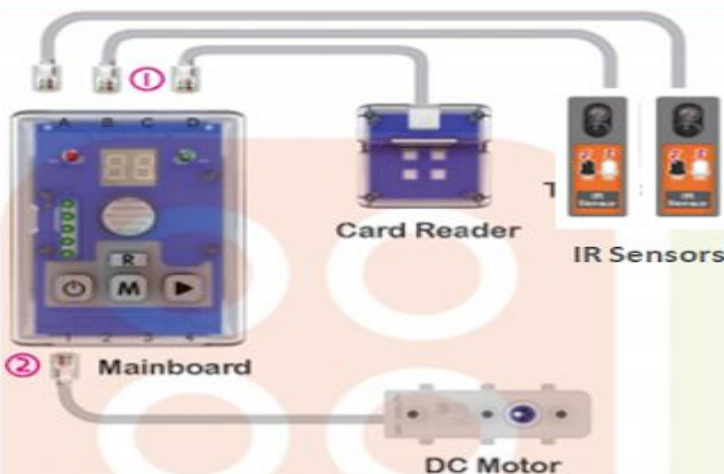








Connect mainboard



① Connect card reader to connector D, and connect IR sensors to connector A, B.

② Connect DC motor to connector 1 and 2.

Programación “Tren”

