



# MY ROBOT TIME

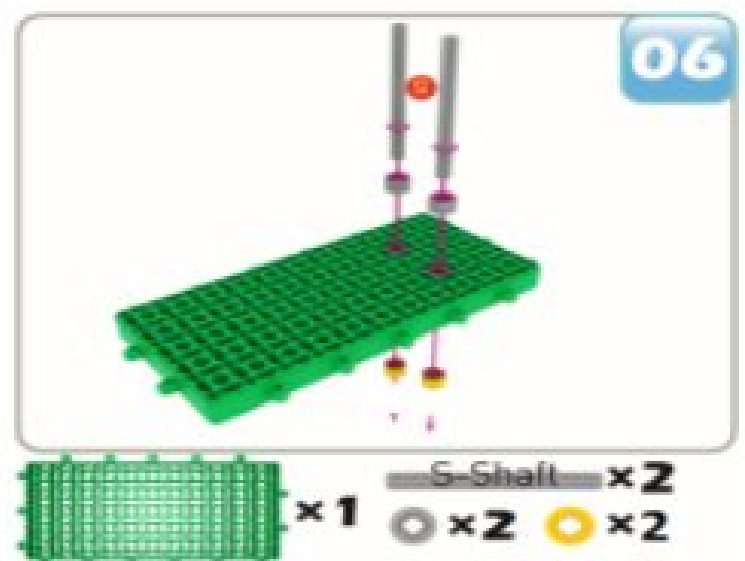
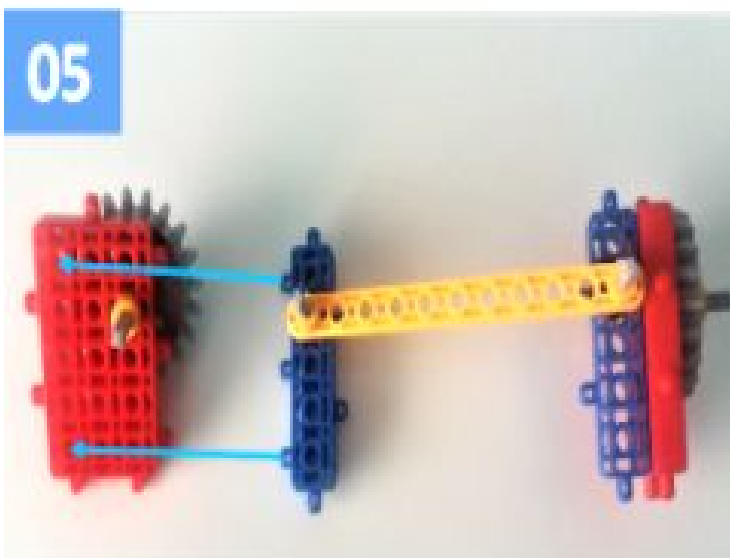
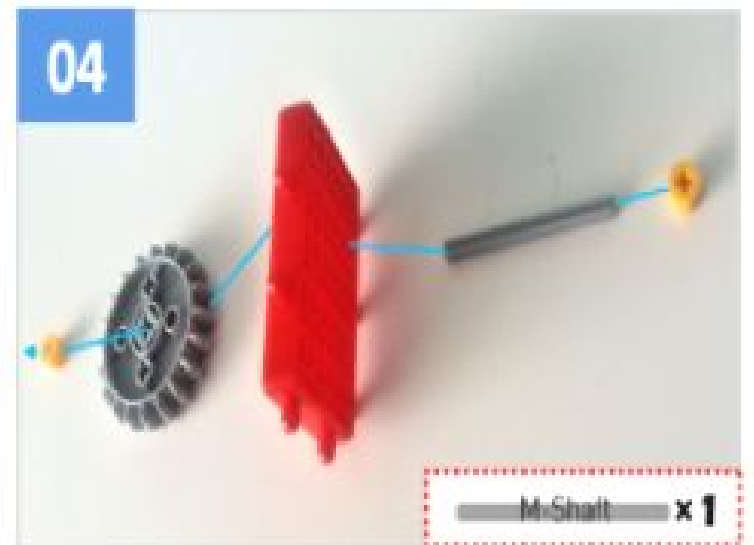
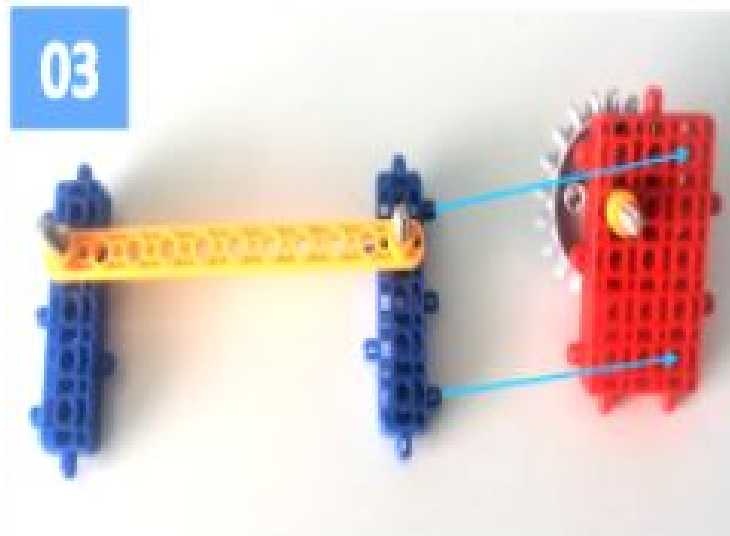
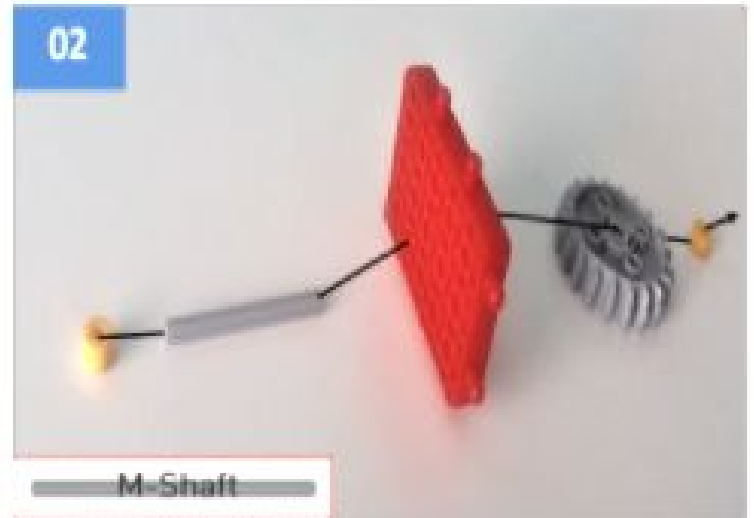
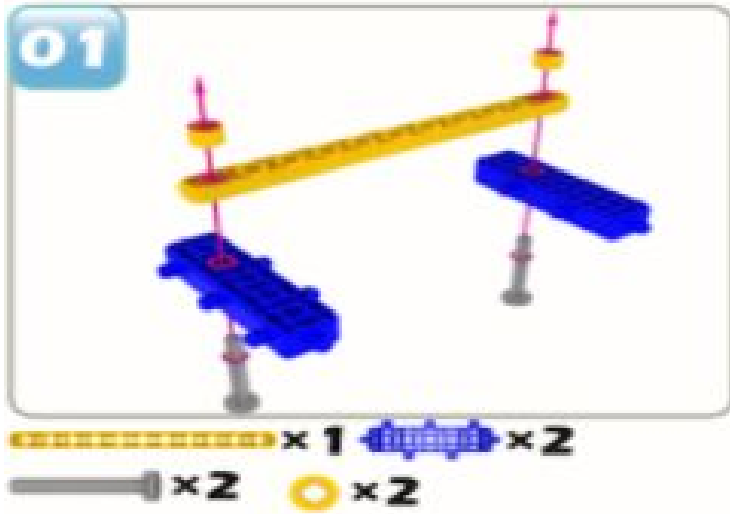
## CONSTRUCCIÓN N° 13

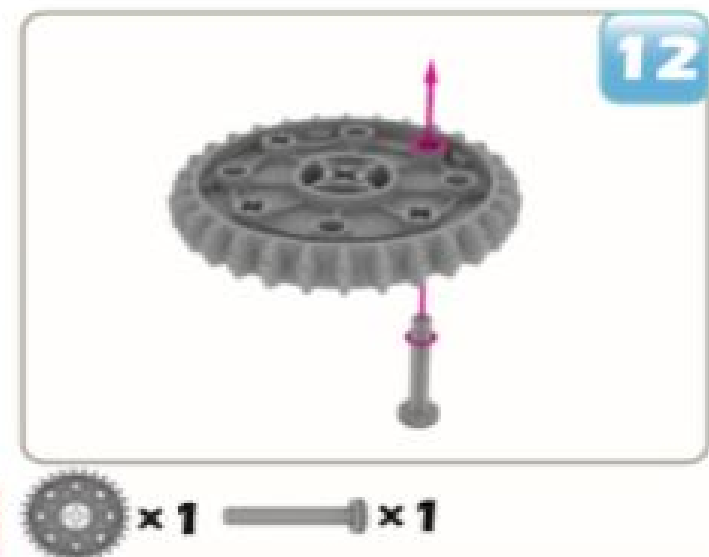
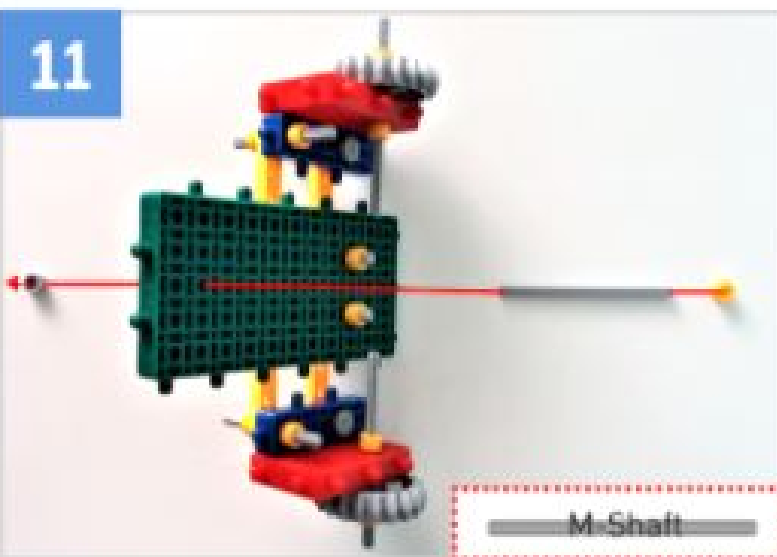
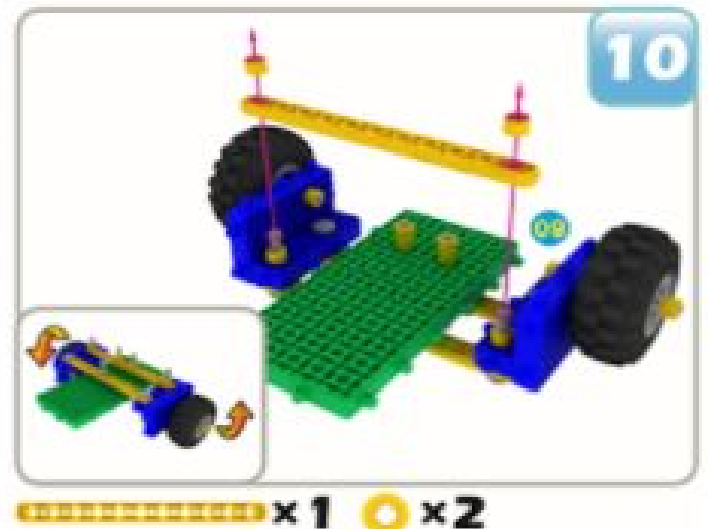
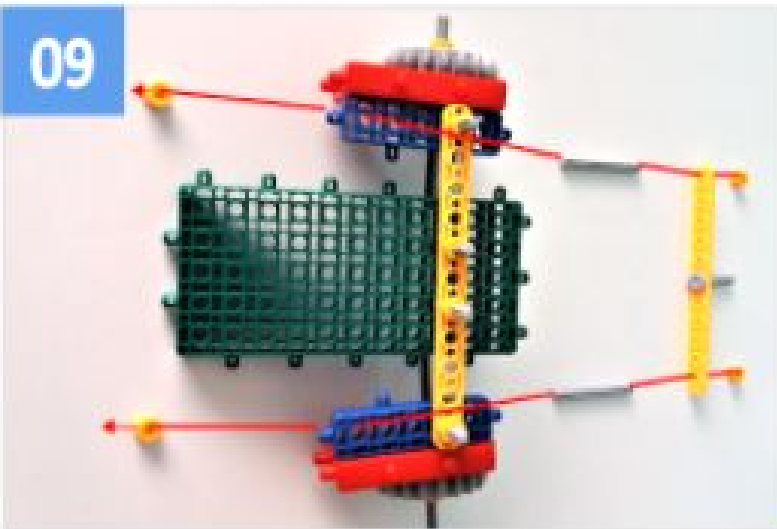
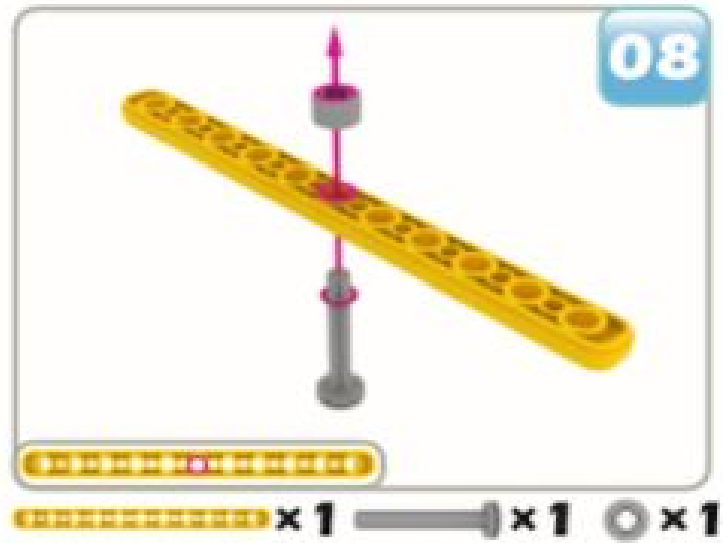
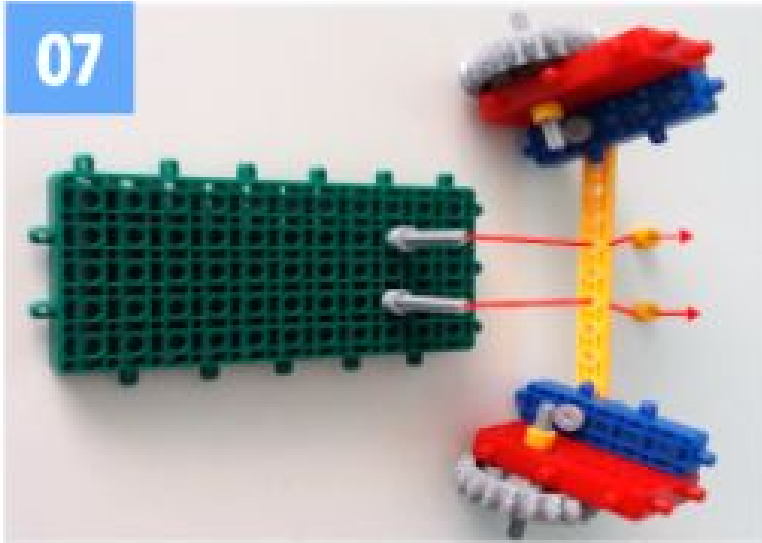
### Coche de carreras

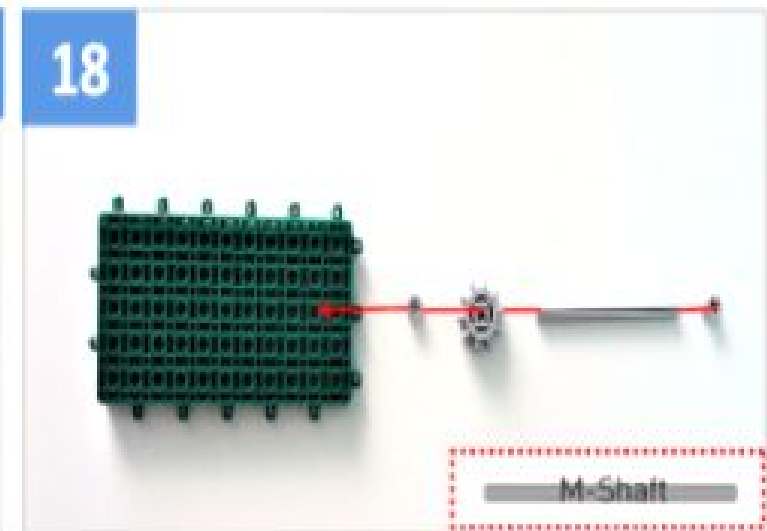
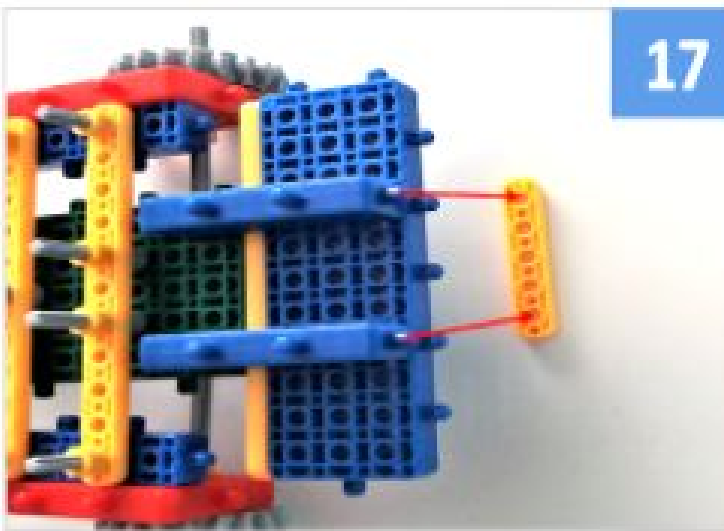
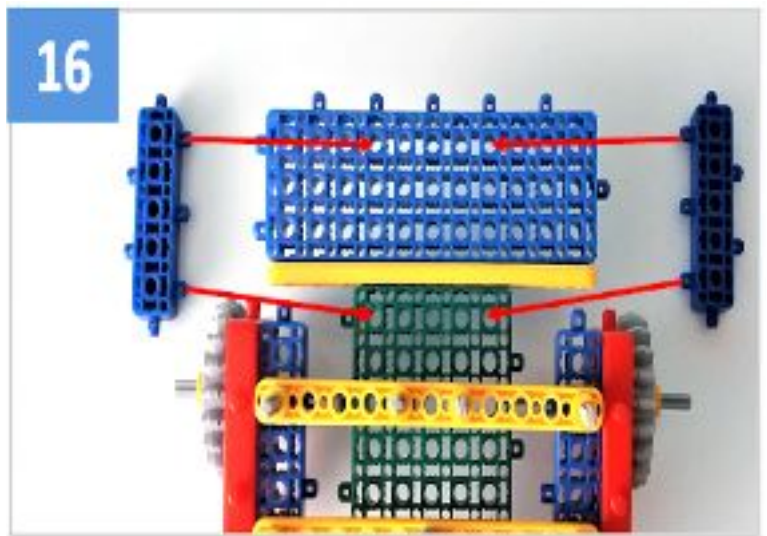
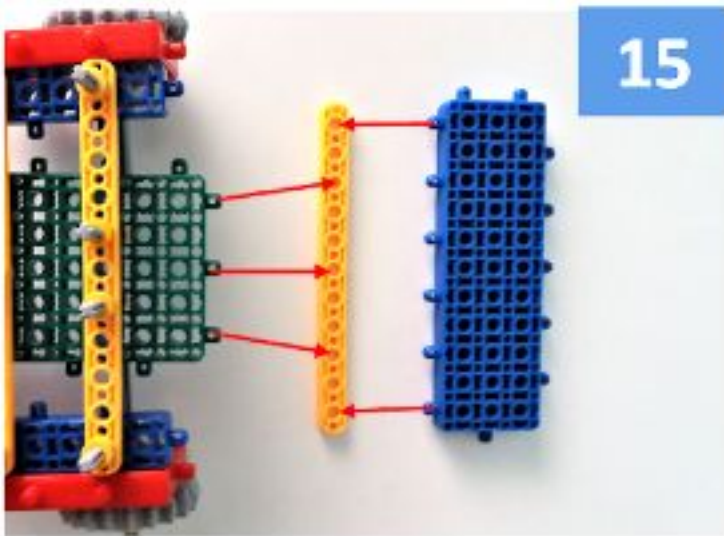
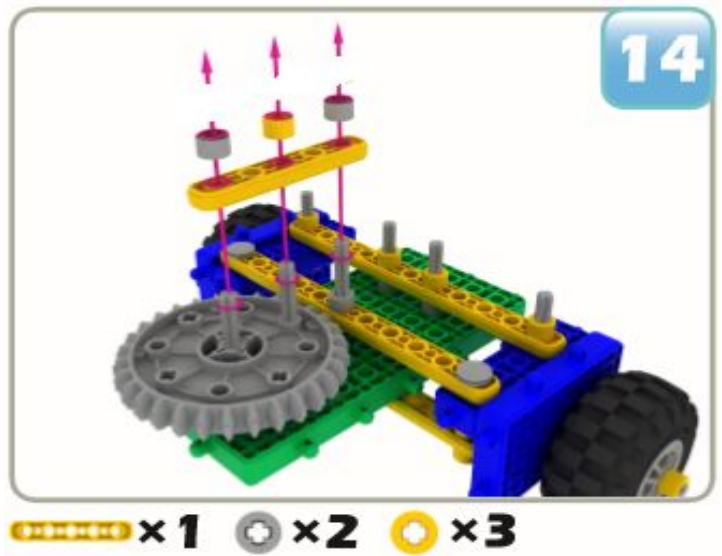
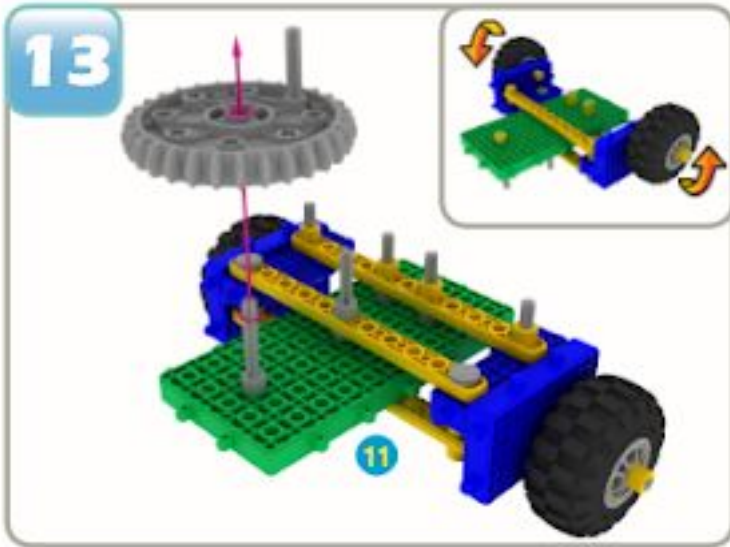
#### **Coche de carreras**

*-Manual de instrucciones-*

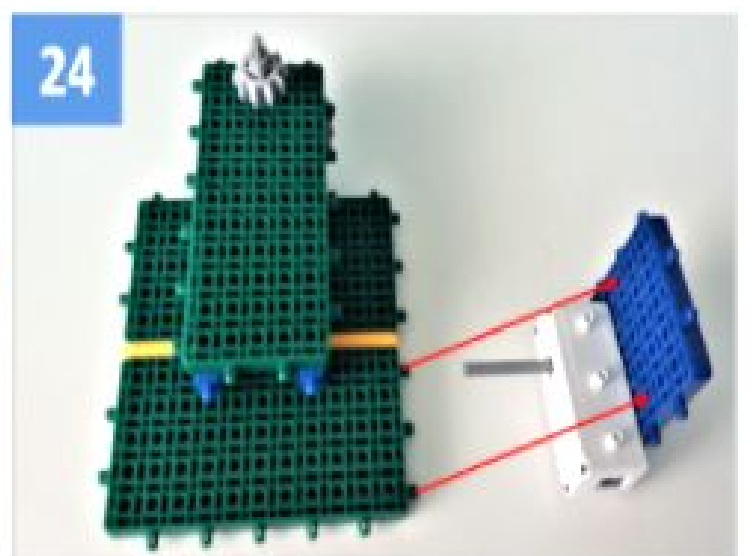
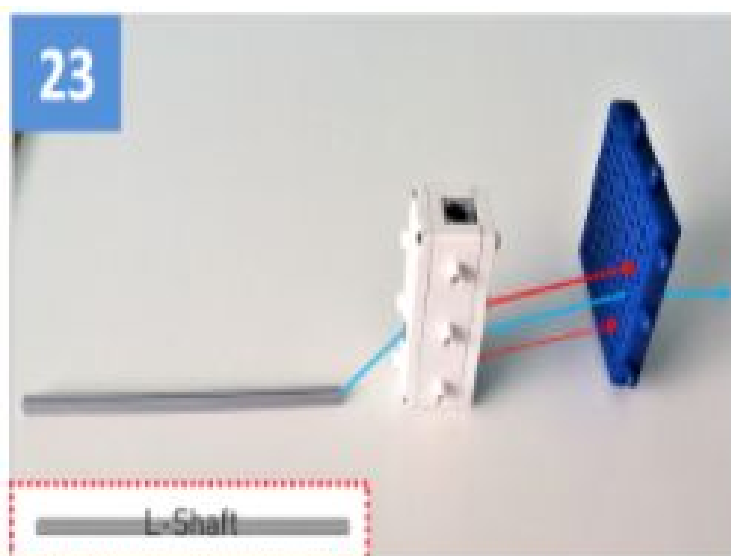
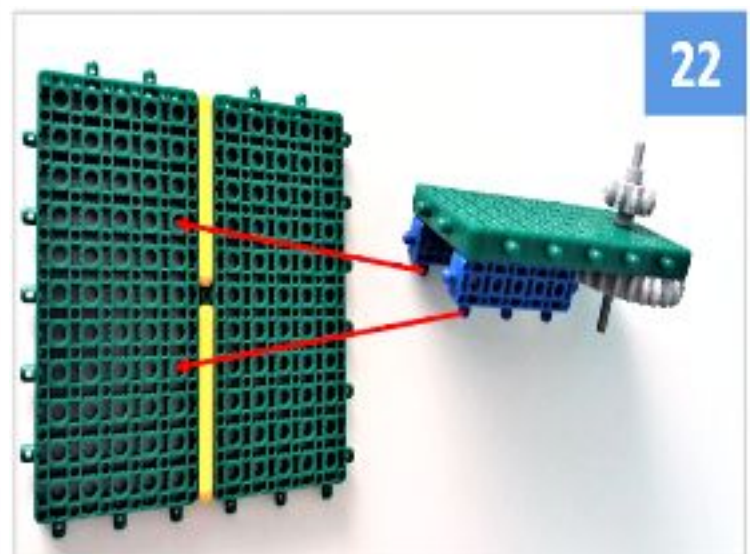
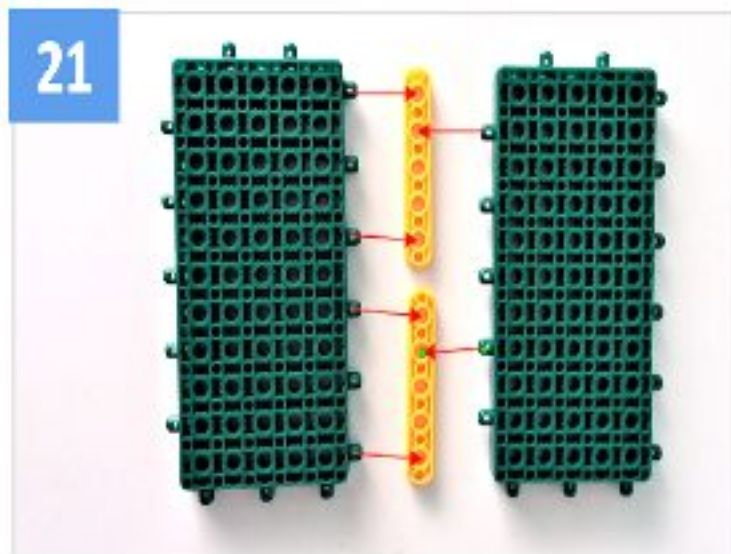
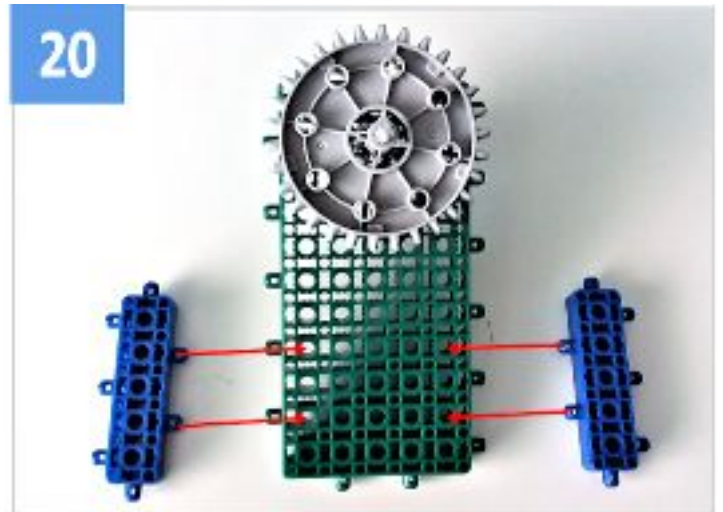
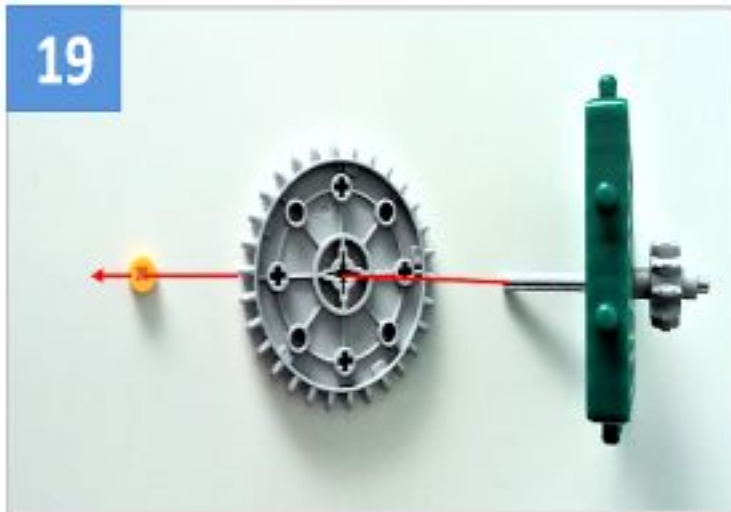


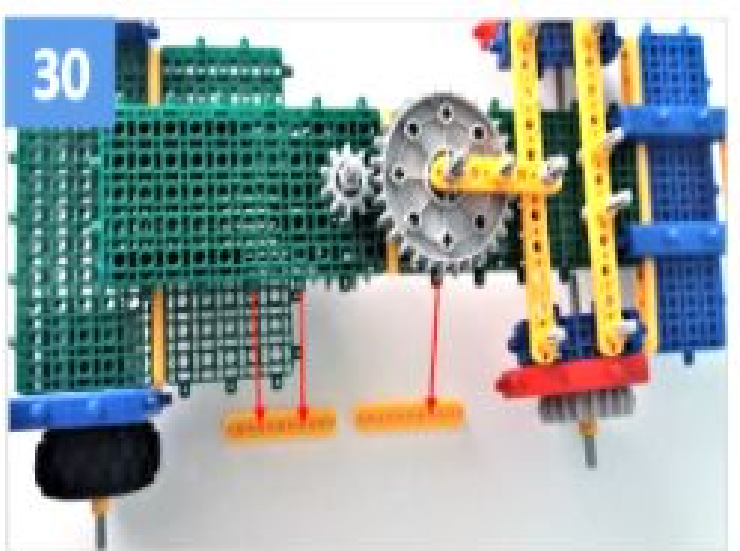
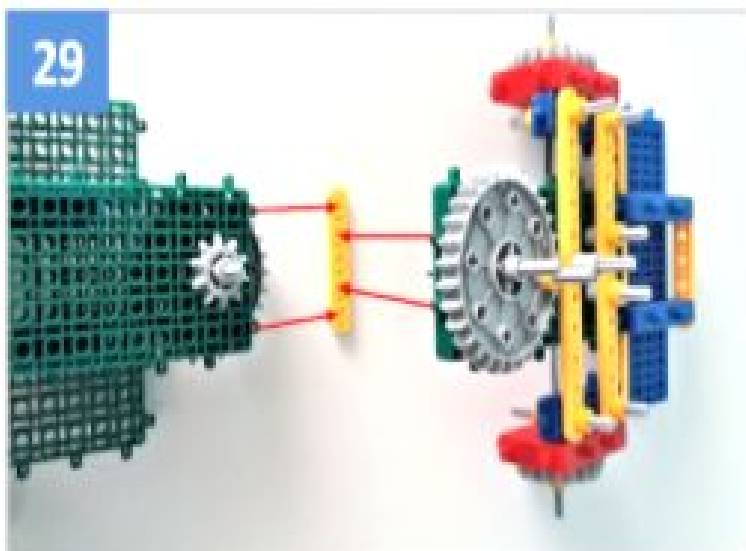
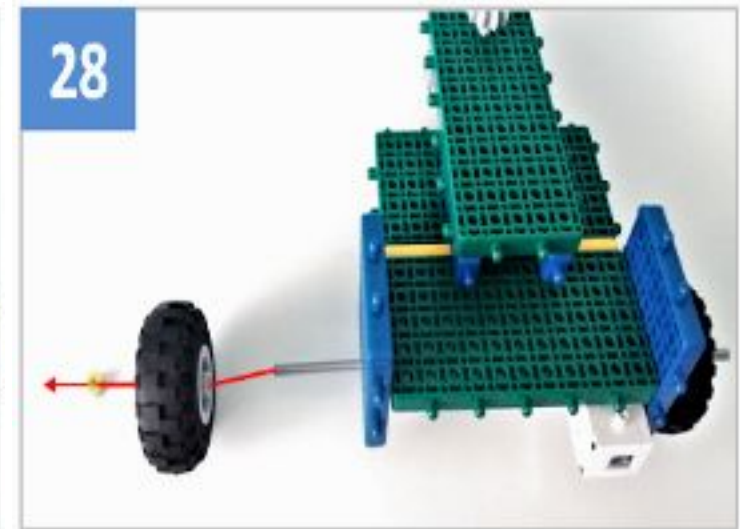
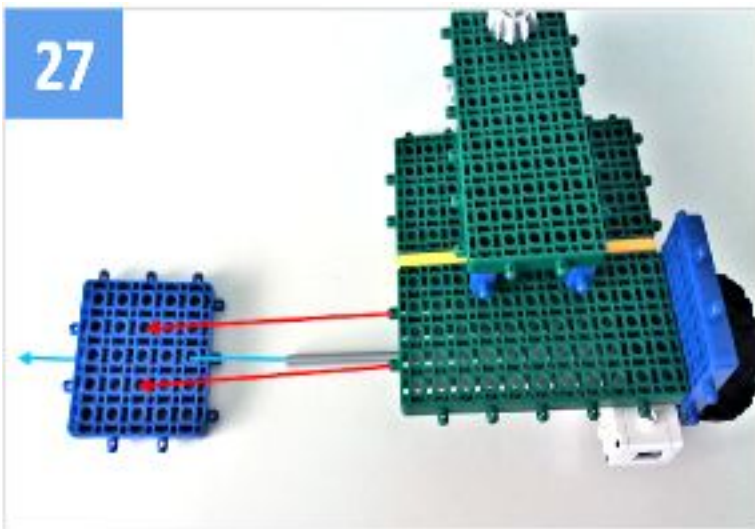
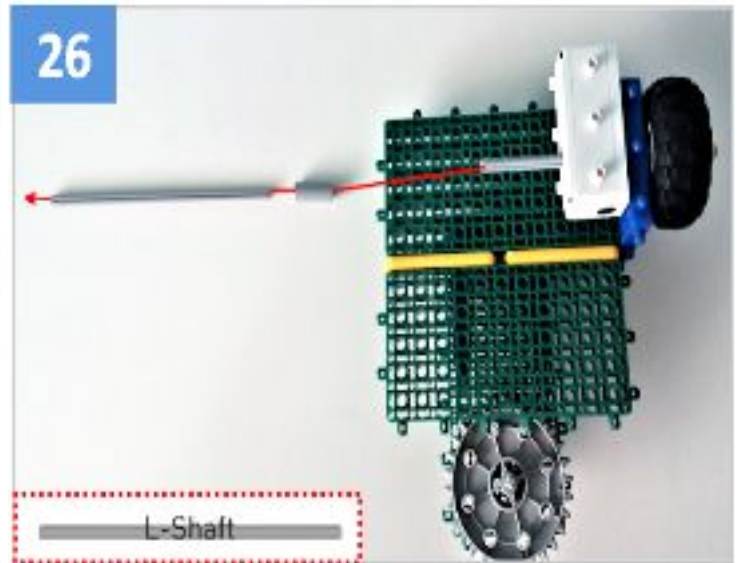
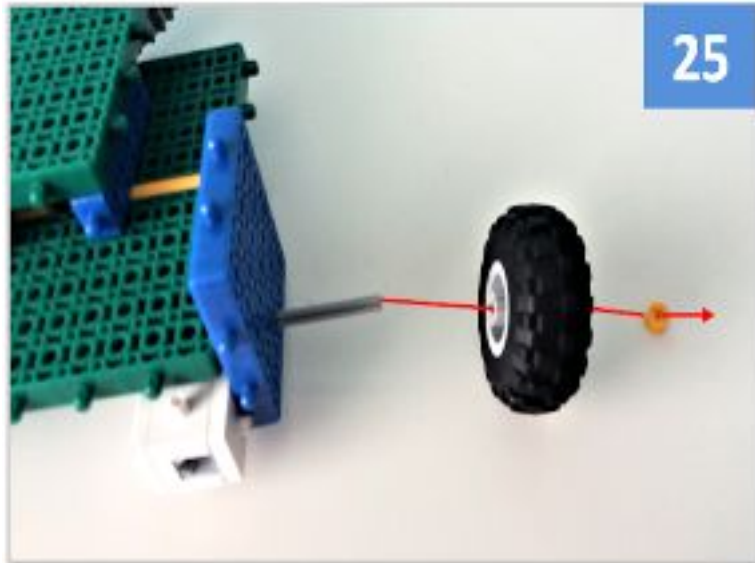




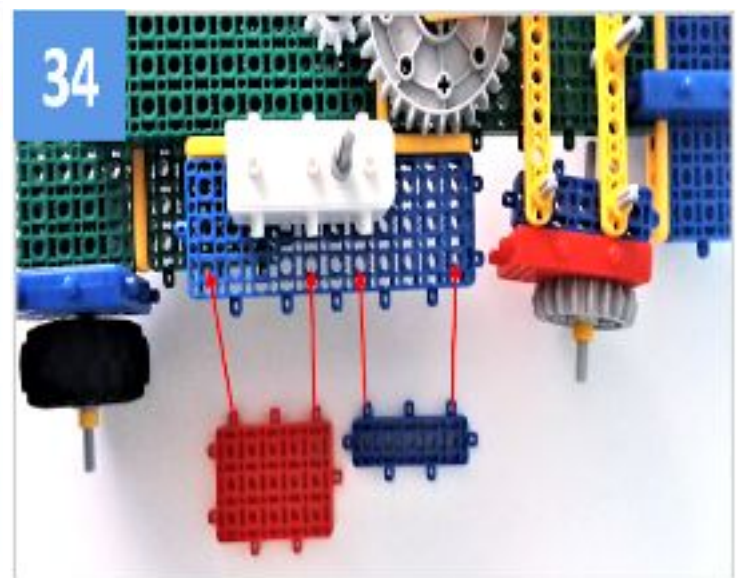
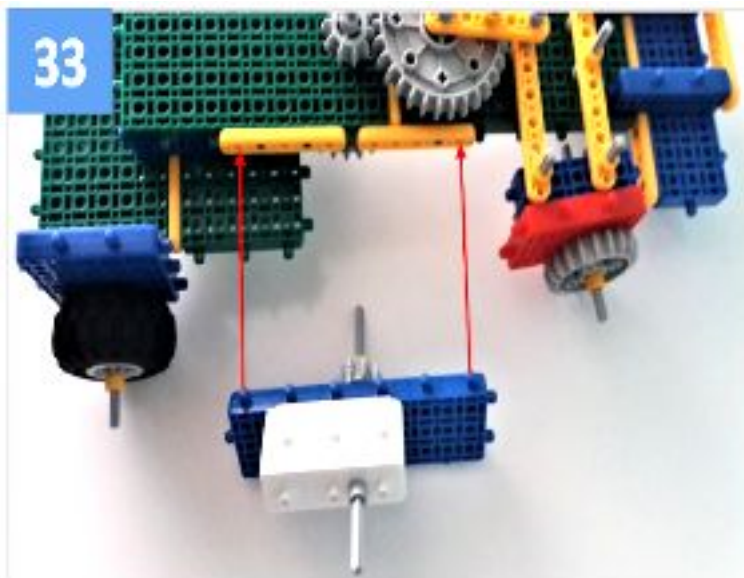
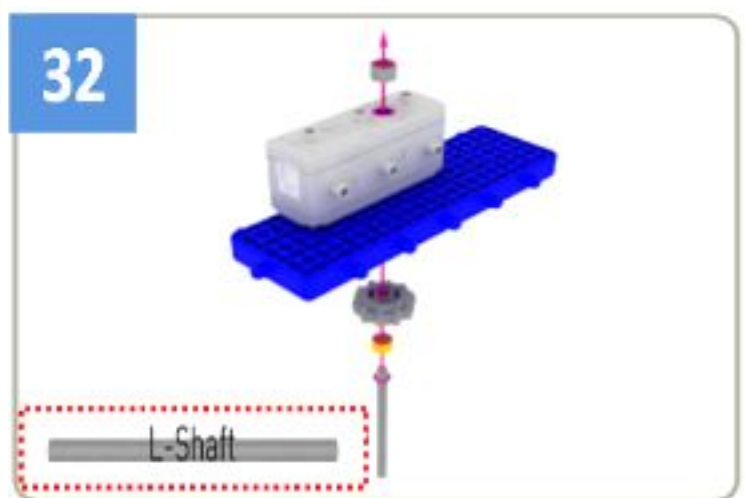
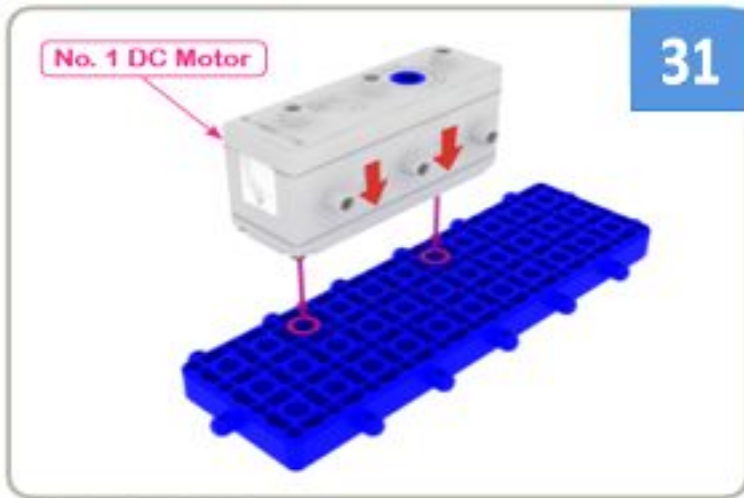


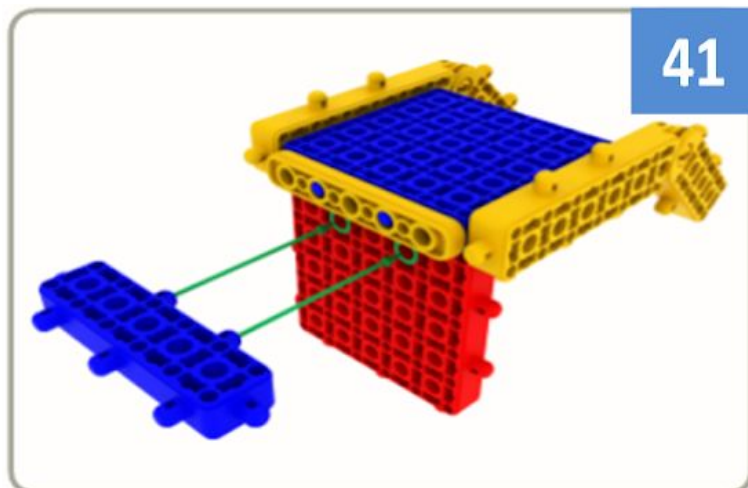
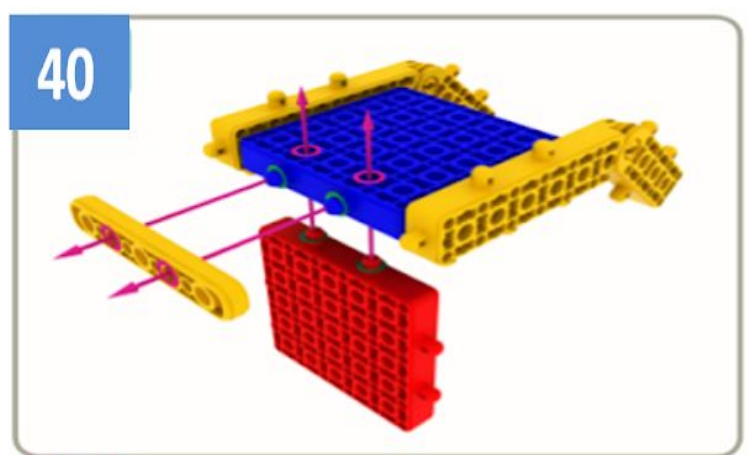
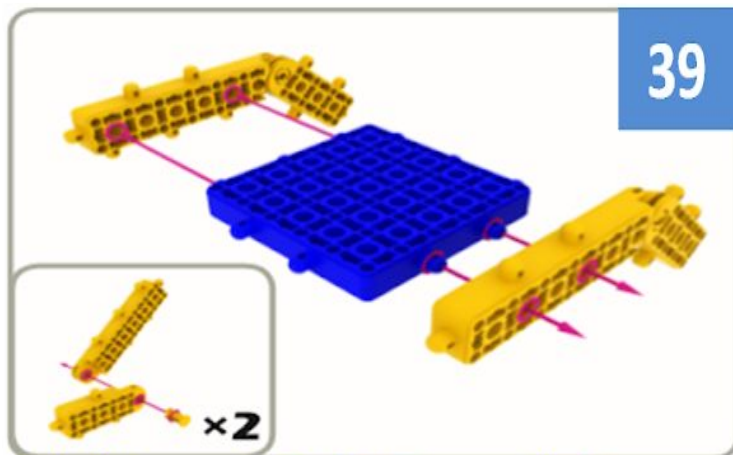
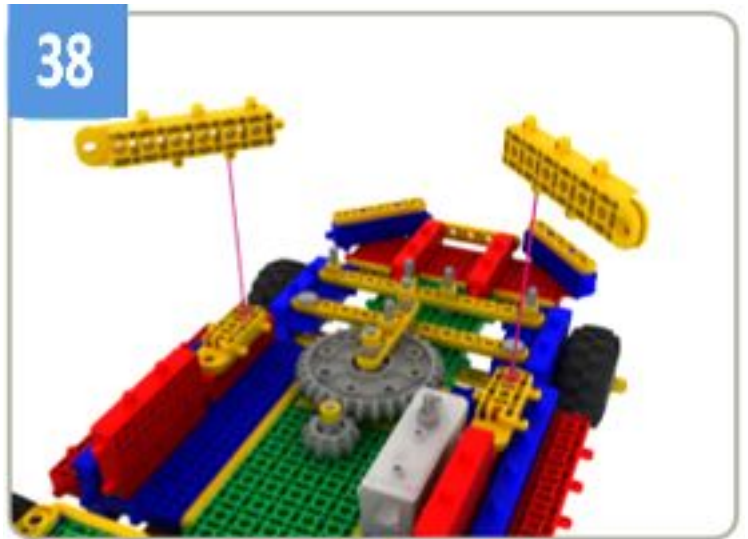




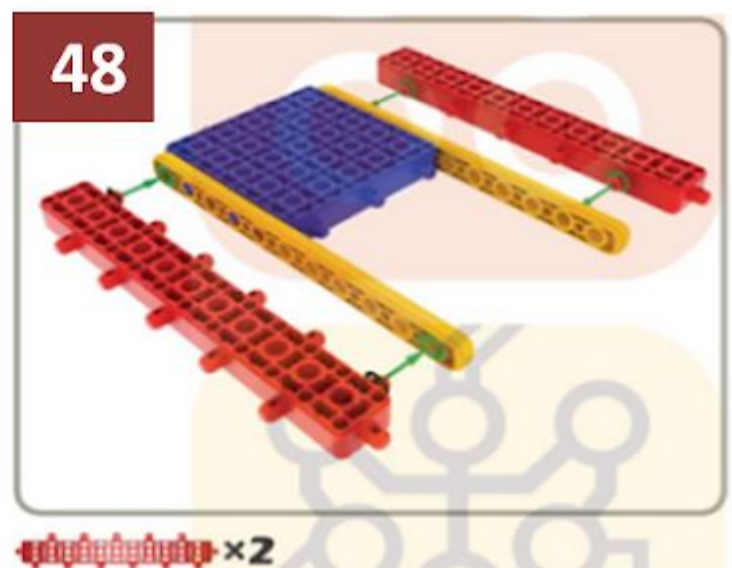
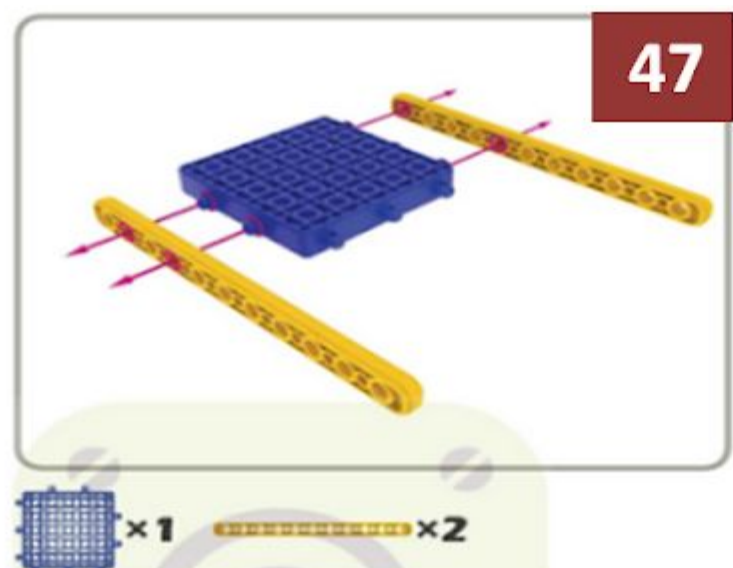
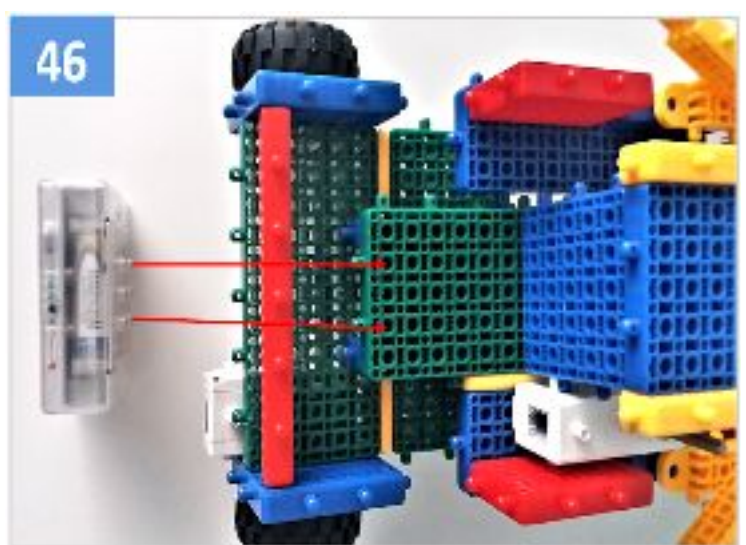
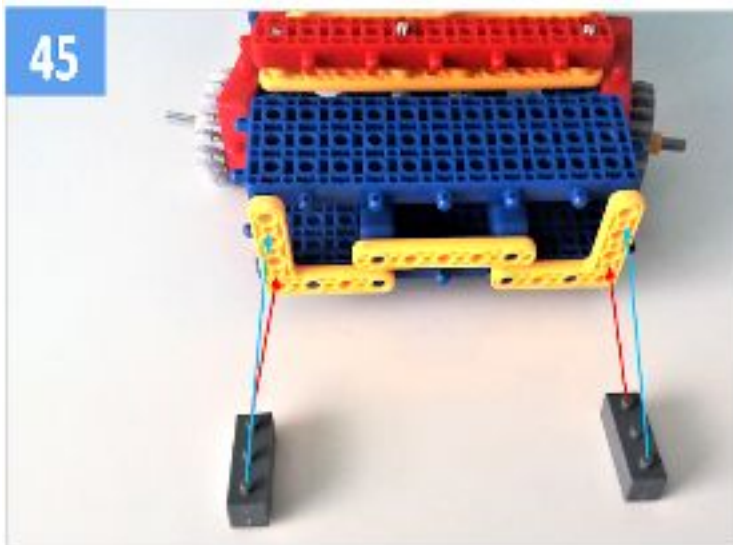
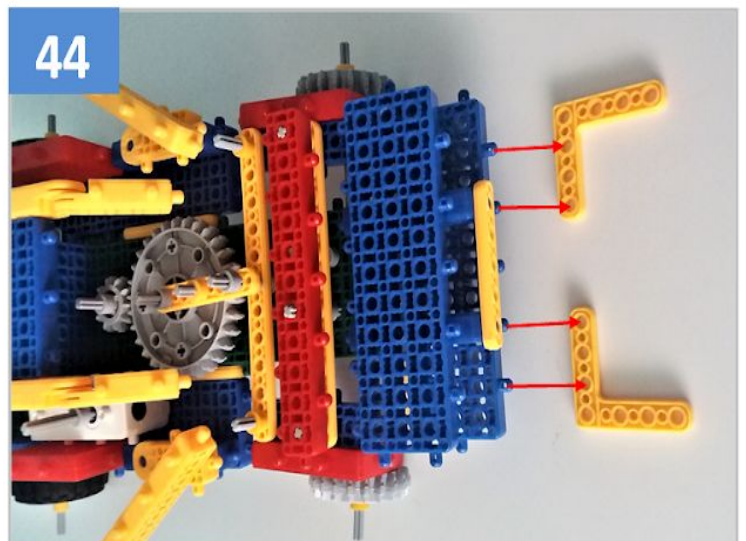
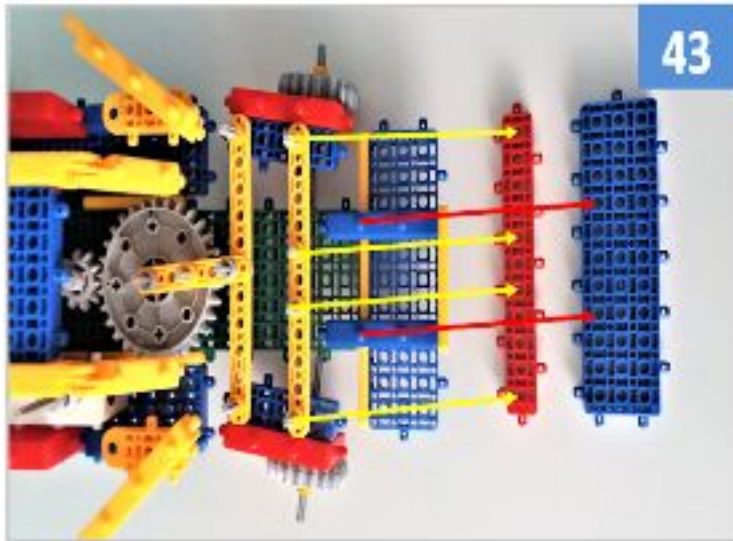


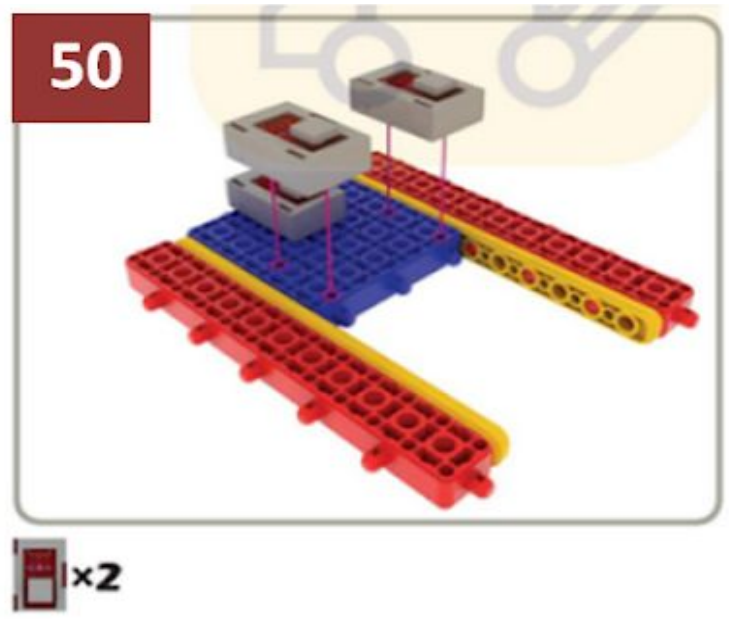
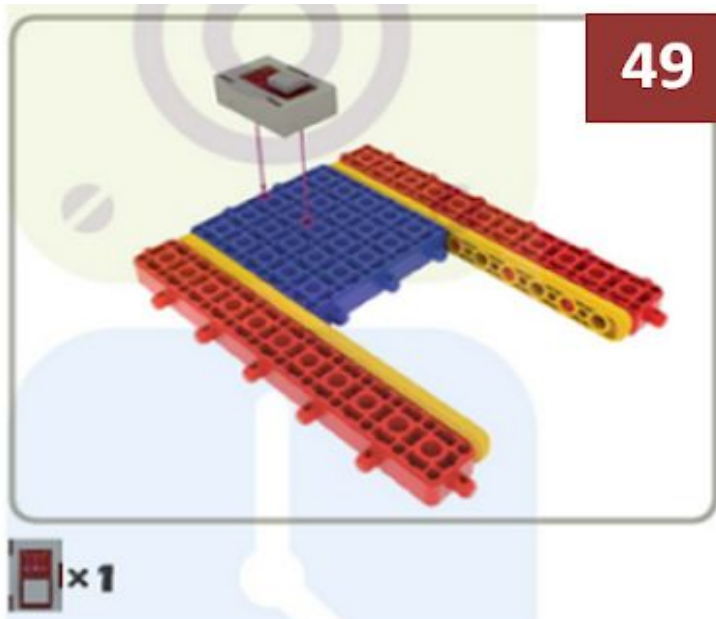








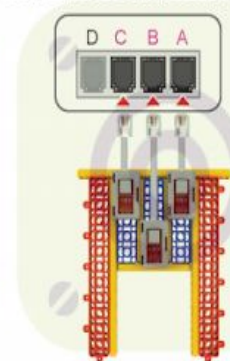




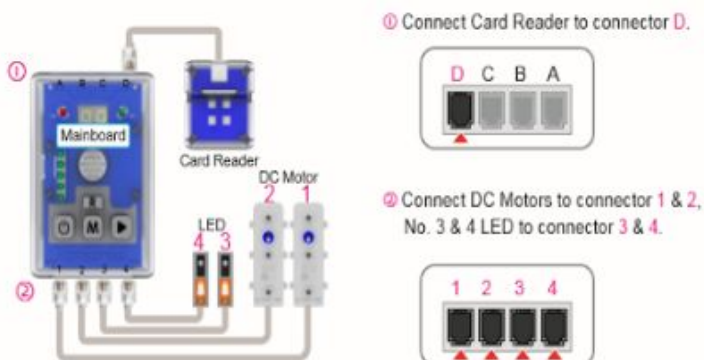
### Connect mainboard / touch sensor

① Connect card reader to connector D.

② Connect 3 pcs of touch sensors to connector A, B, C.



### Connect mainboard





# Programación del coche de carreras

