



MY ROBOT TIME

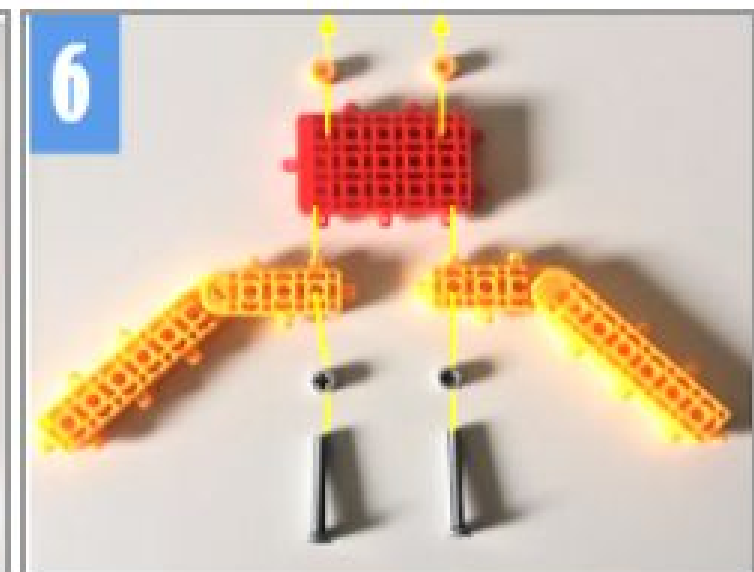
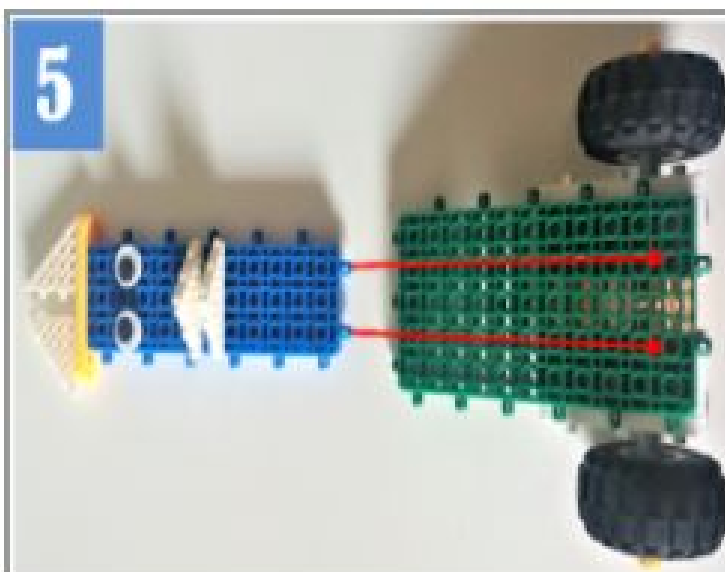
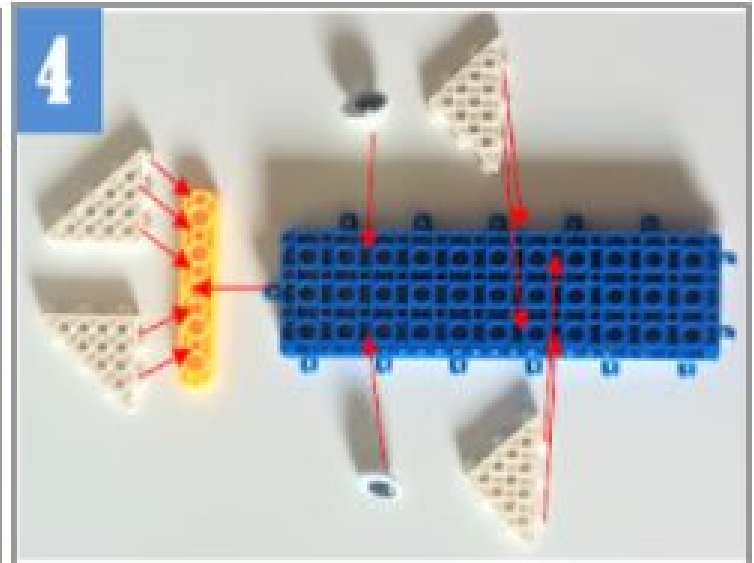
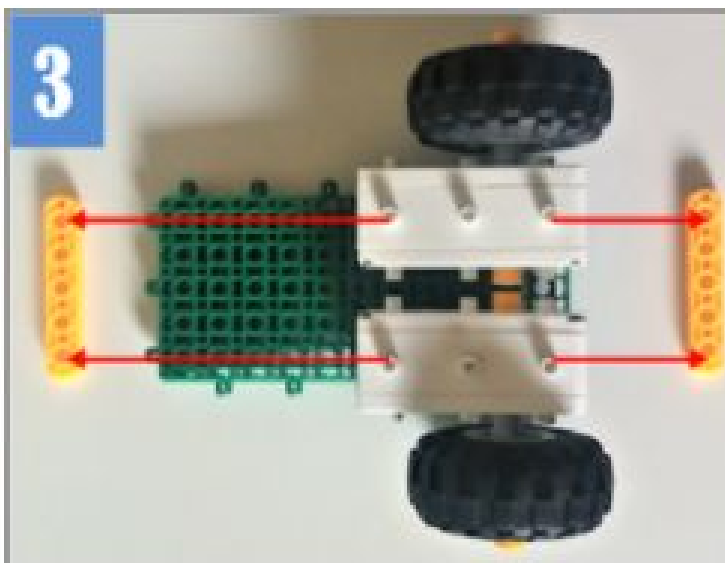
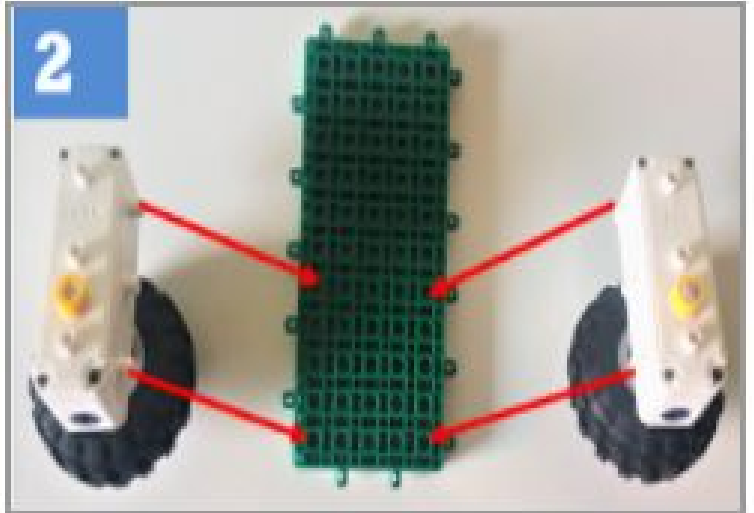
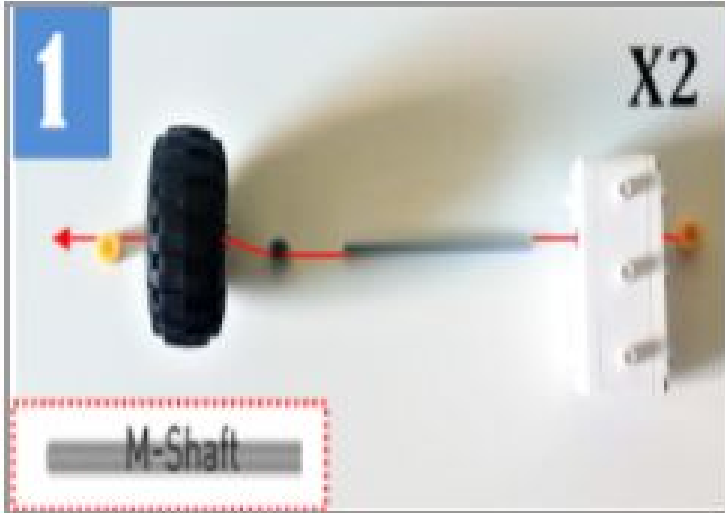
CONSTRUCCIÓN N° 2

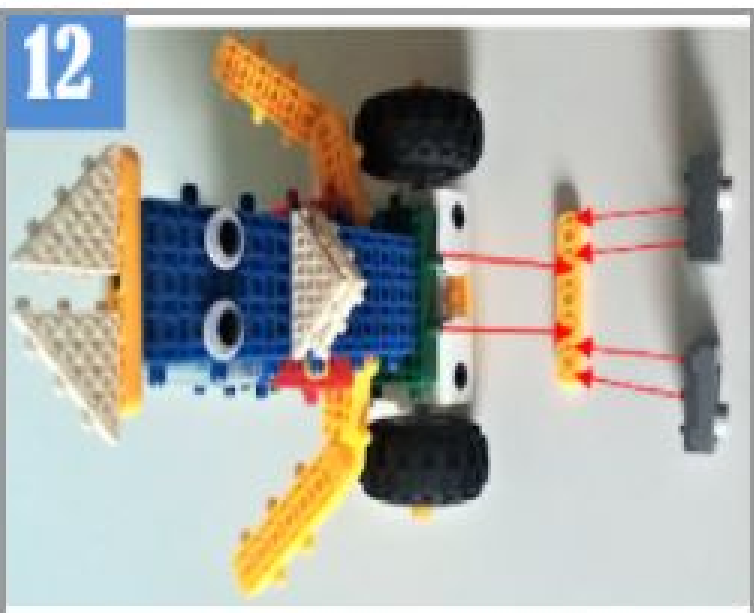
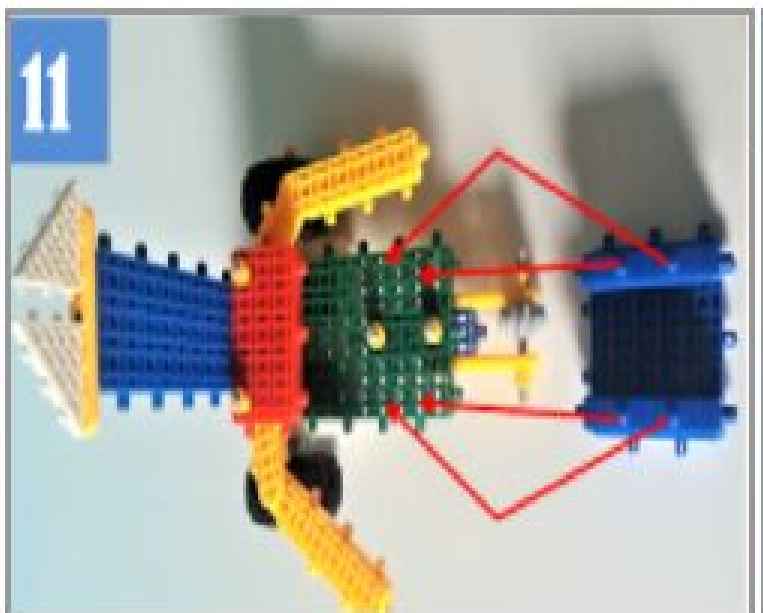
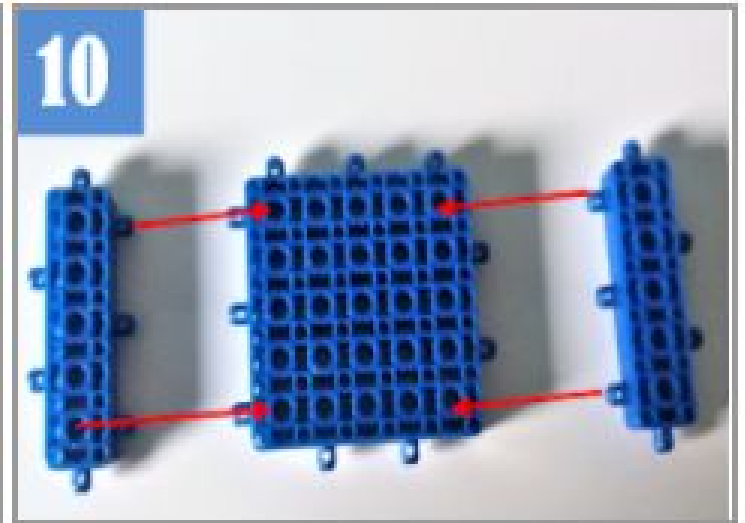
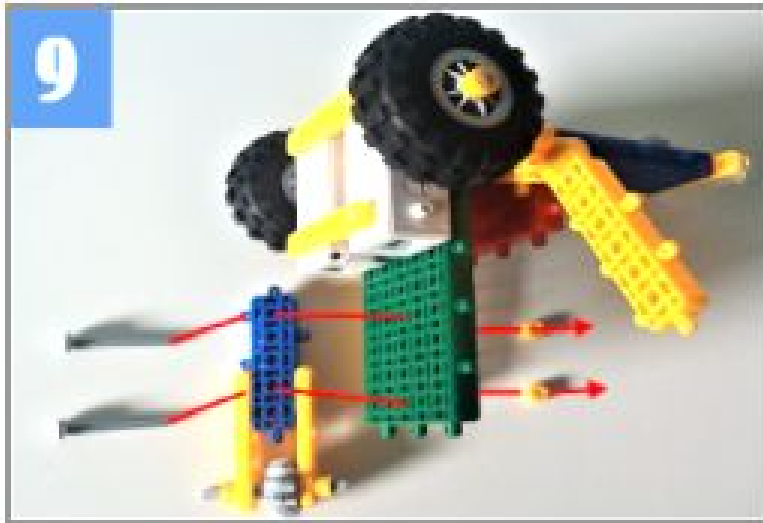
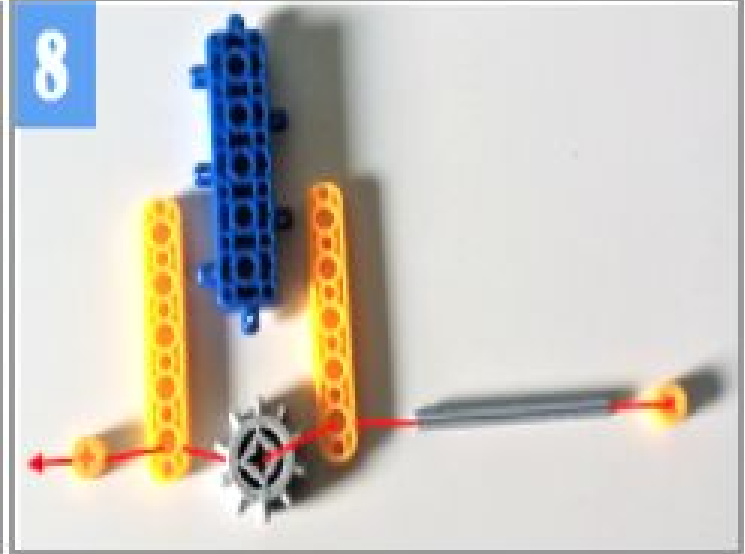
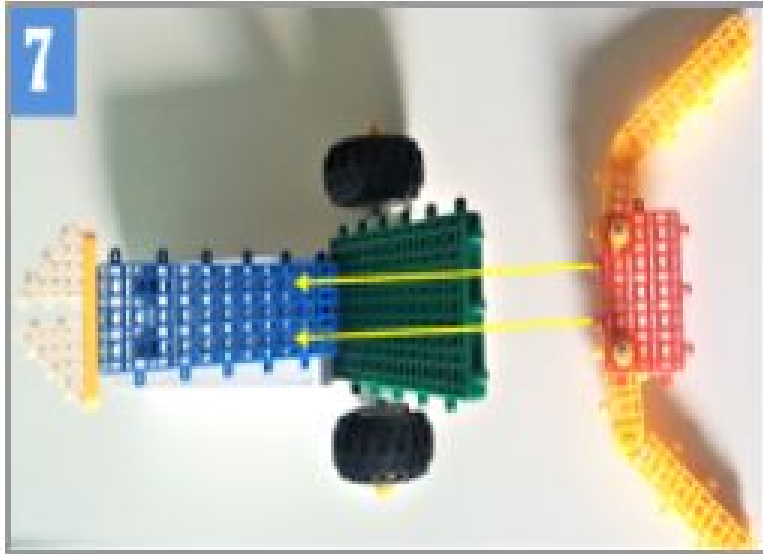
Pato robótico

“Pato robótico”

-Manual de instrucciones-



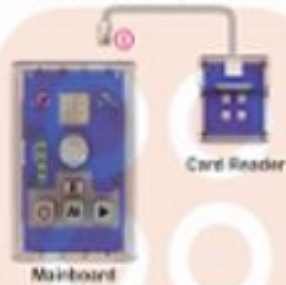






Connect mainboard / touch sensor

- ① Connect card reader to connector D.

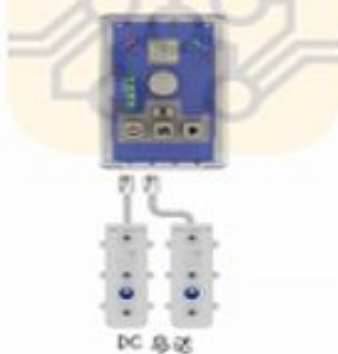


- ② Connect 2 pcs of touch sensors to connector A, B.



Connect DC motor

- ① Connect DC motor to connector 1, 2.



- ② Connect left DC motor to connector 1. Connect right DC motor to connector 2.



Programación “Pato robótico”

