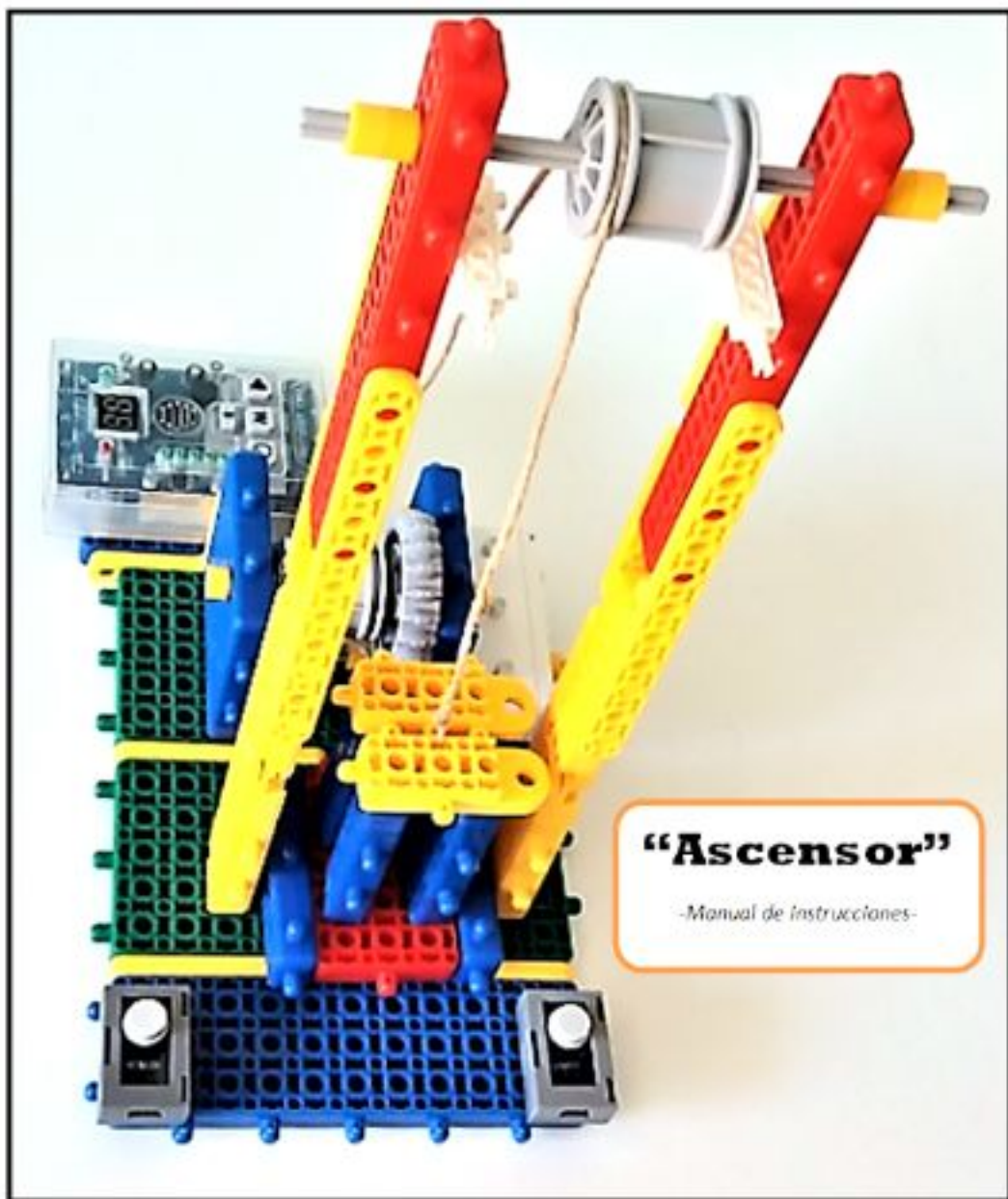




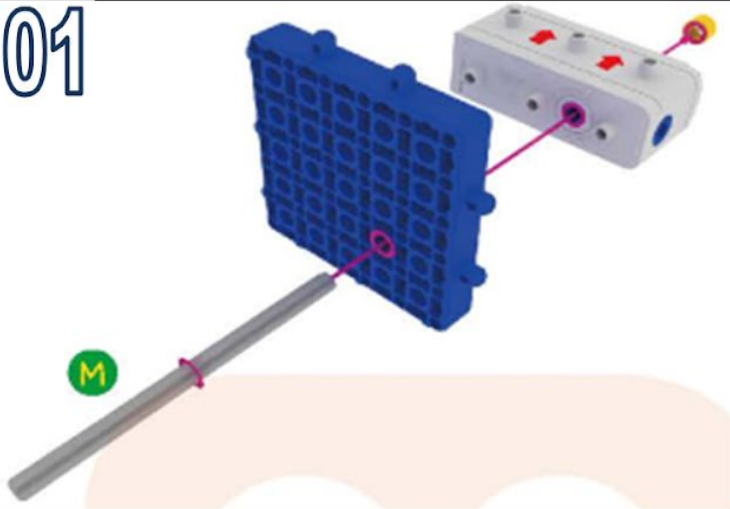
my robot time

## CONSTRUCCIÓN N° 5

### Ascensor



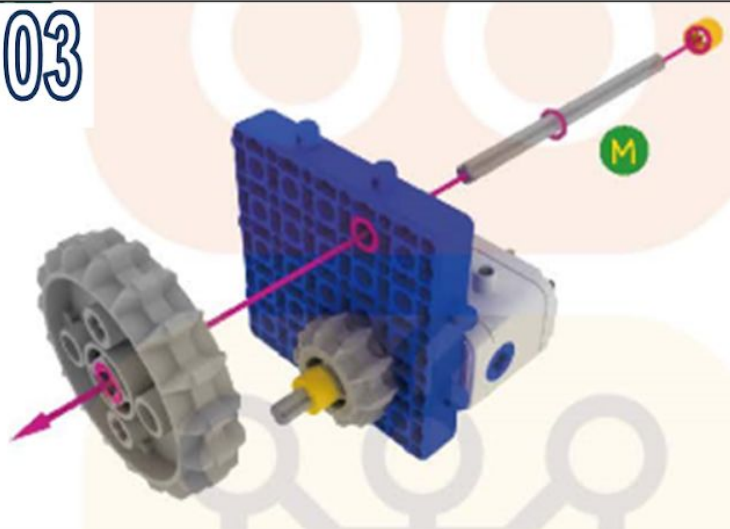
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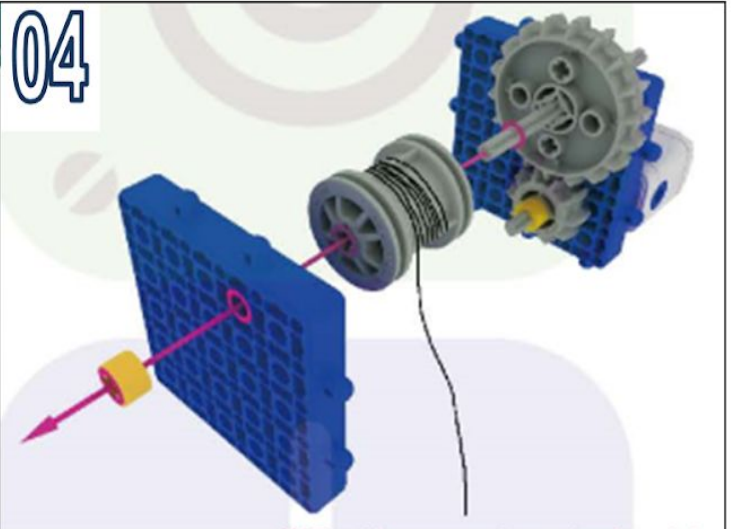
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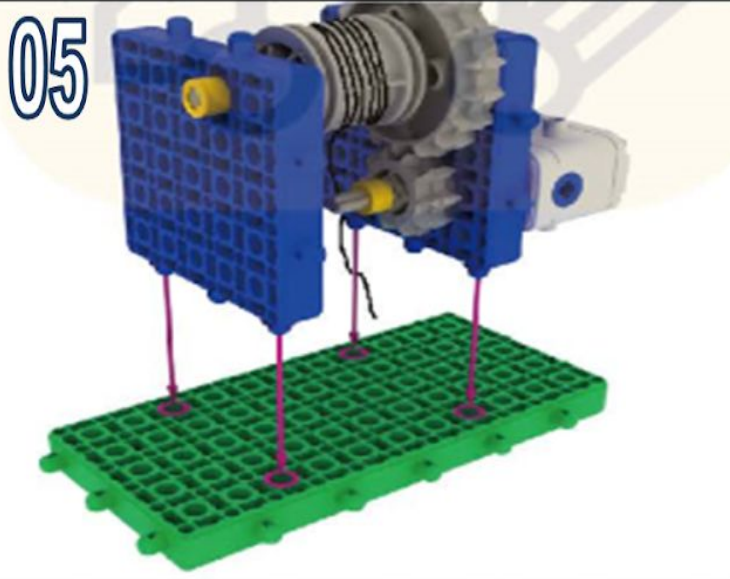
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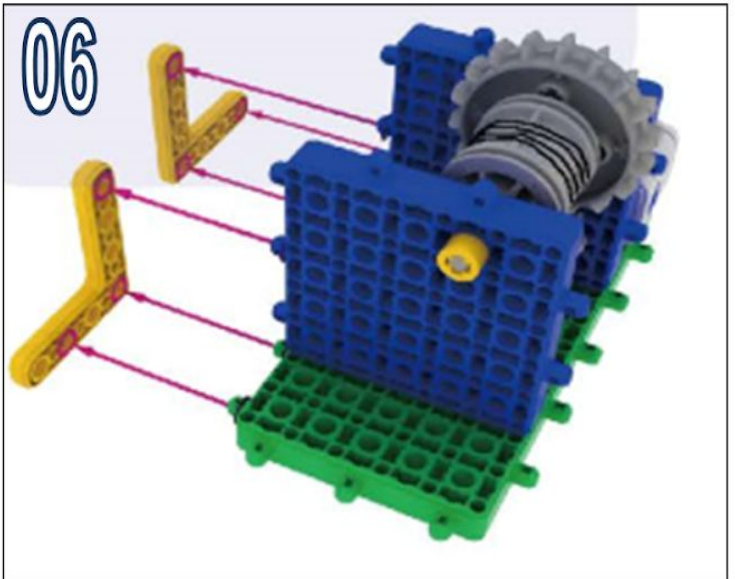
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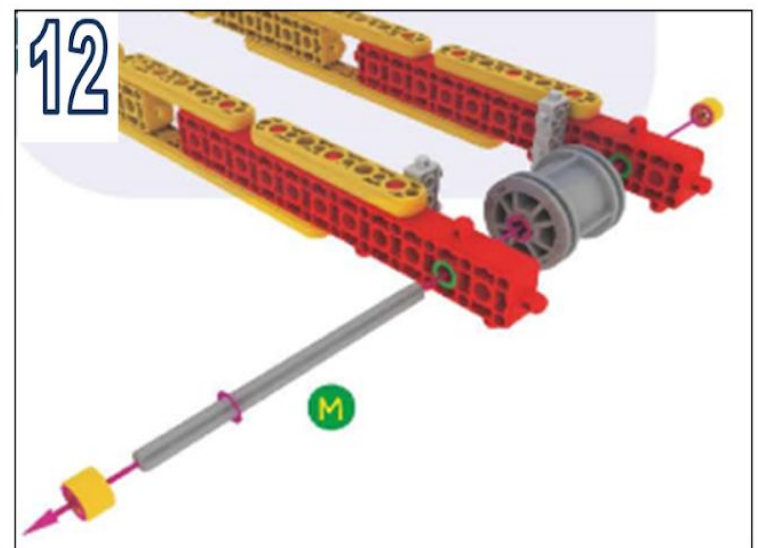
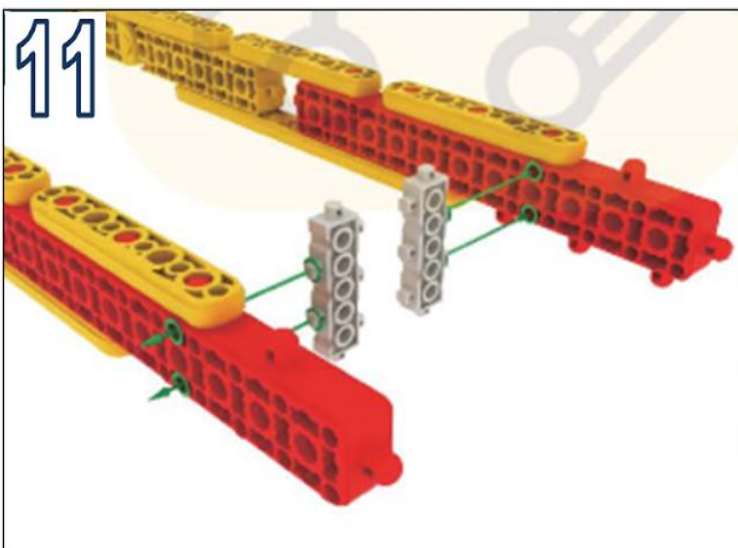
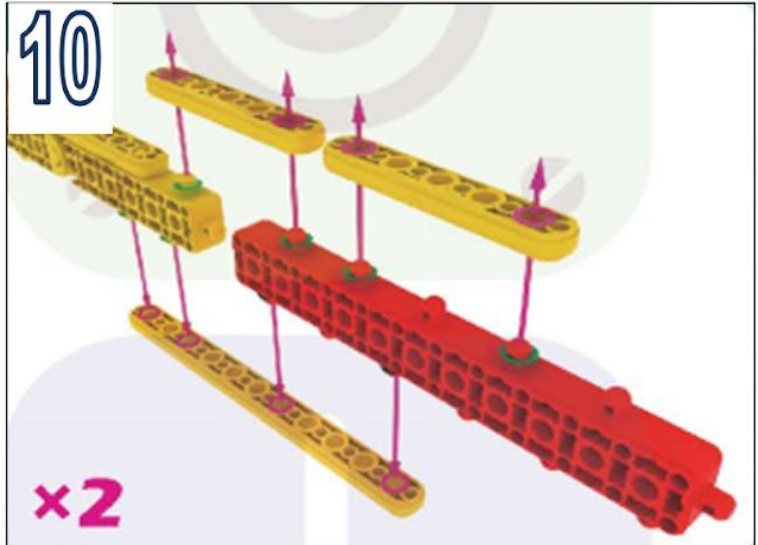
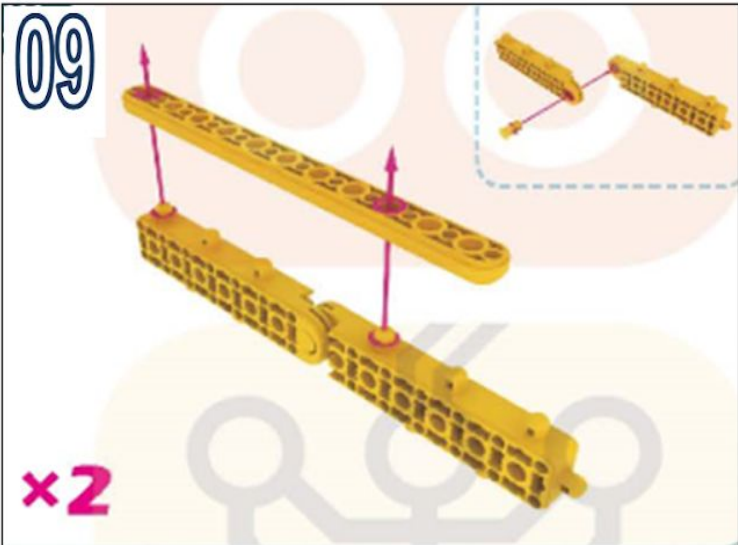
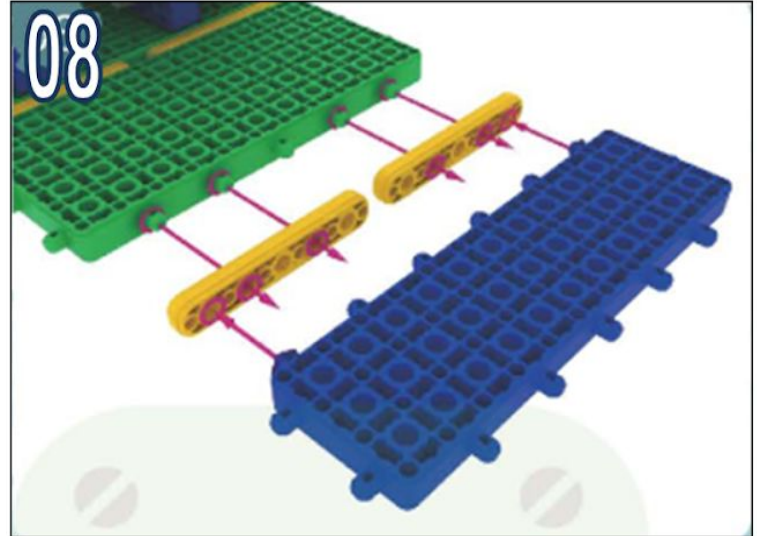
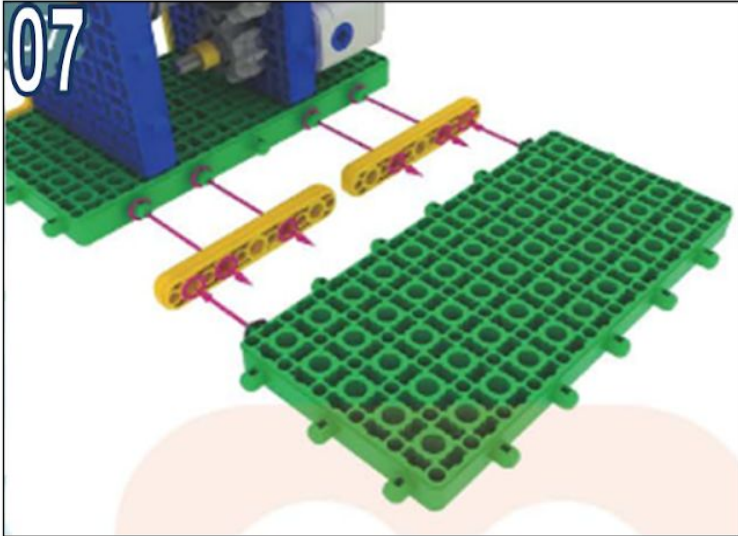
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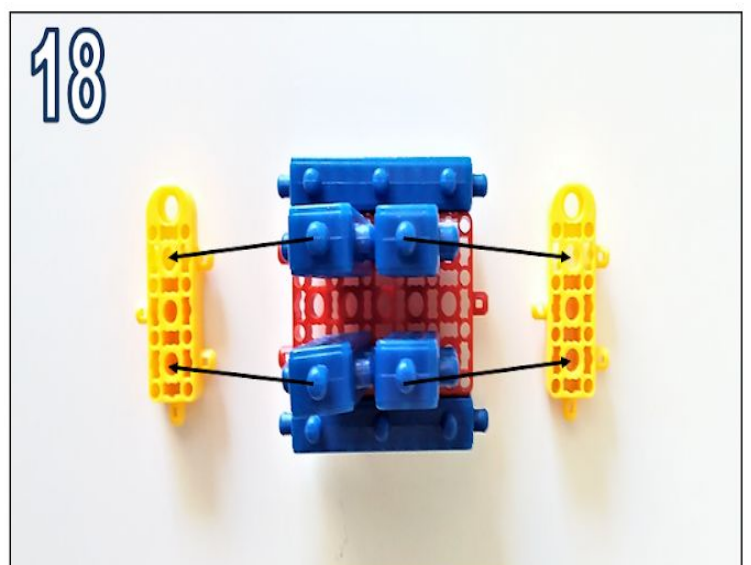
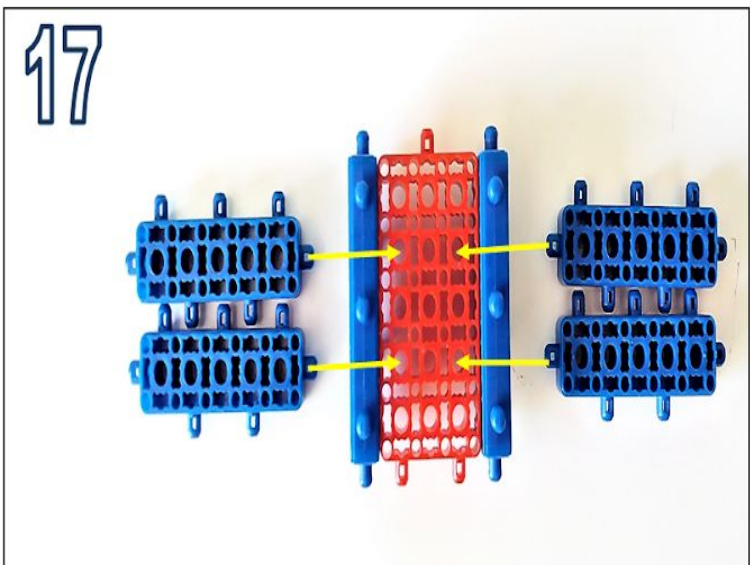
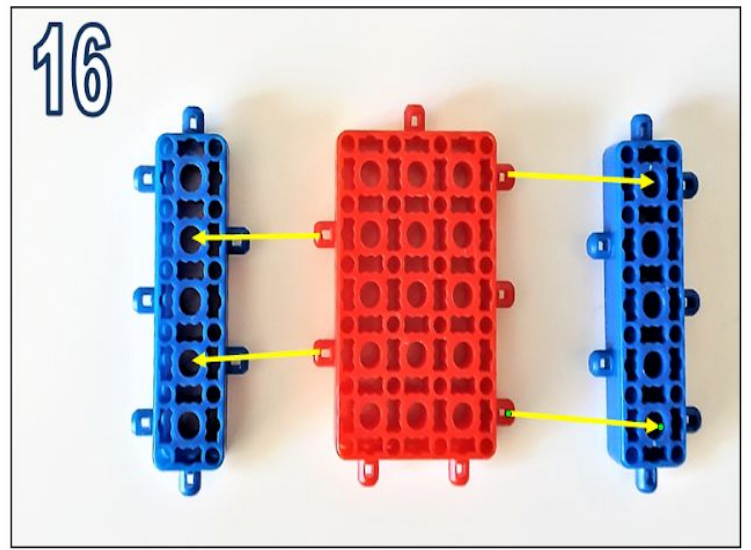
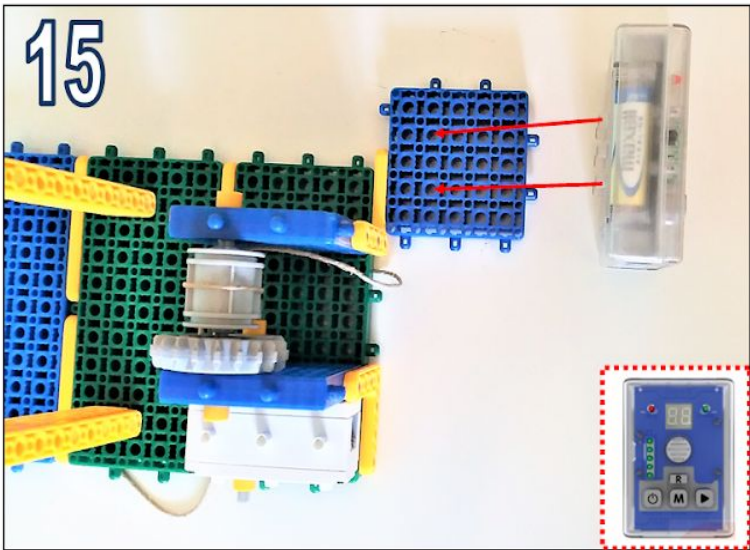
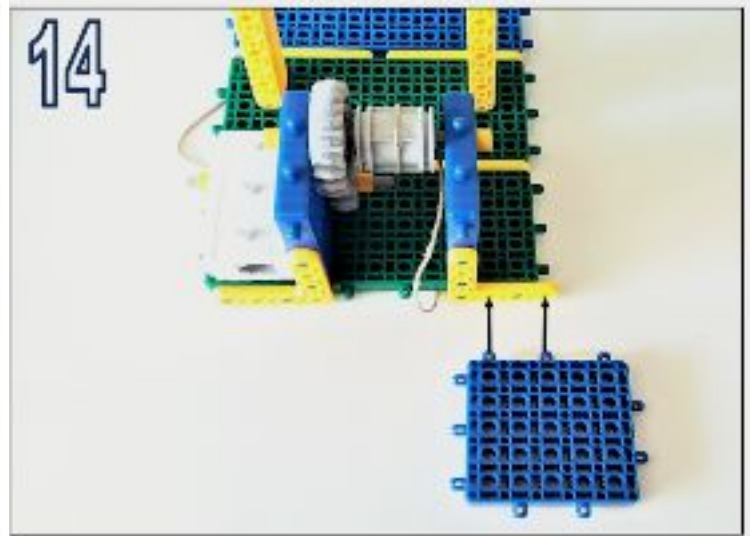
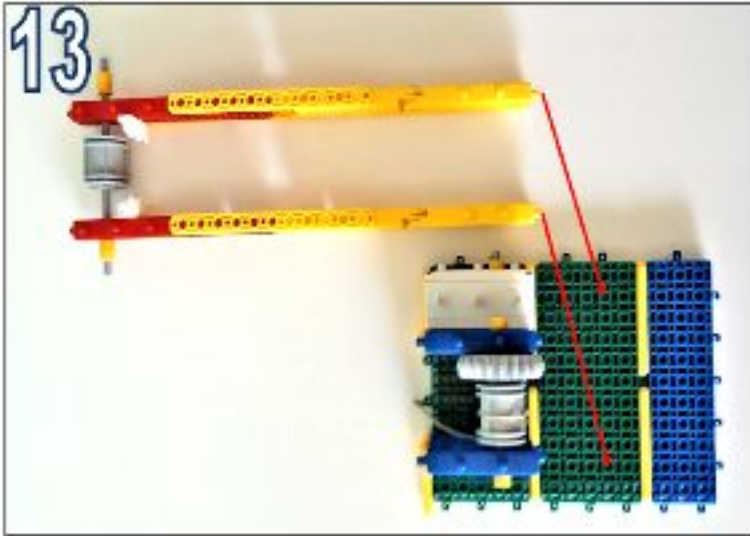


06

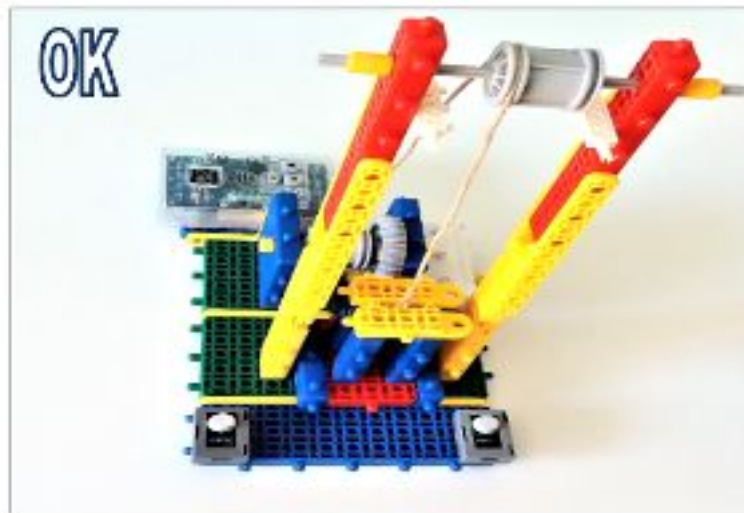
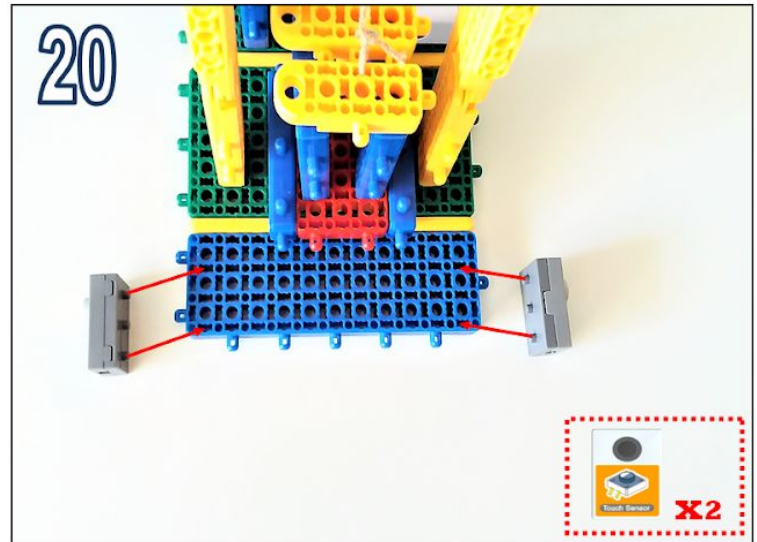
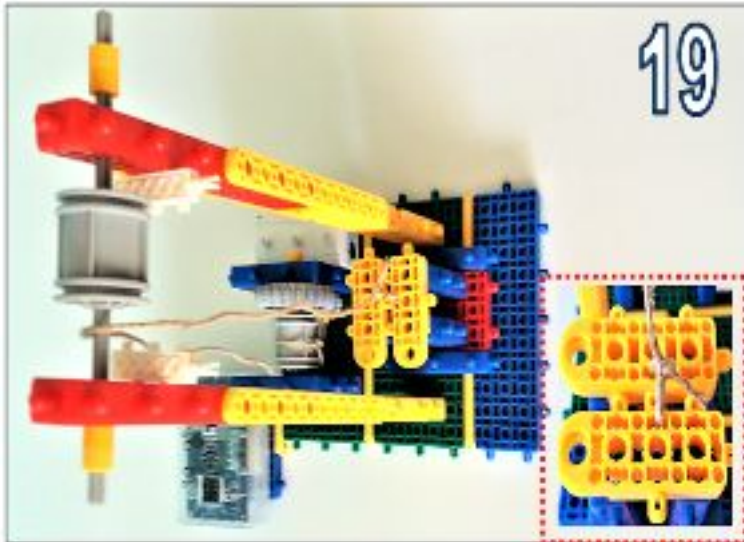




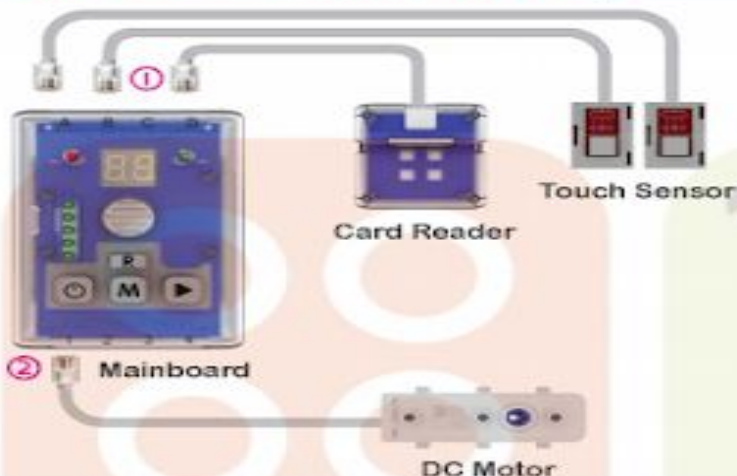




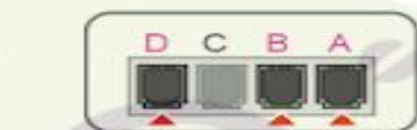




## Connect mainboard



① Connect card reader to connector D, and connect touch sensors to connector A, B.



② Connect DC motor to connector 1.



# Programación “Ascensor”

