



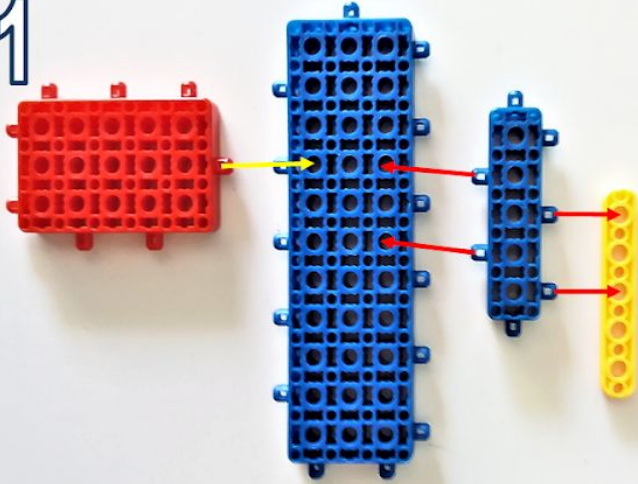
# my robot time

## CONSTRUCCIÓN N° 14

### Casa robótica

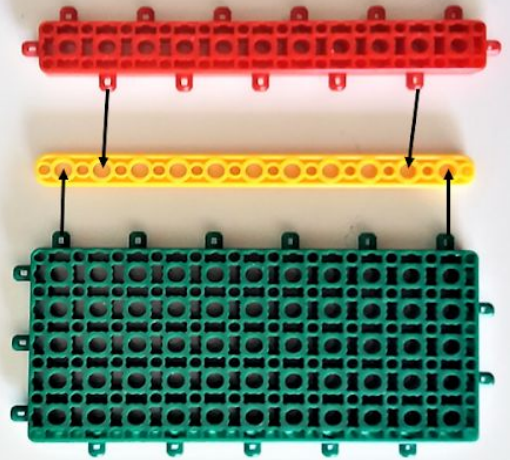


01

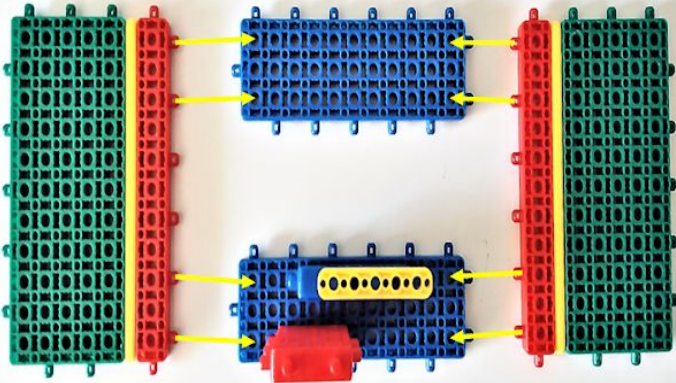


02

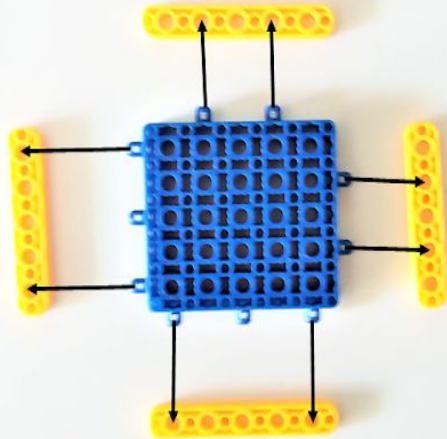
X2



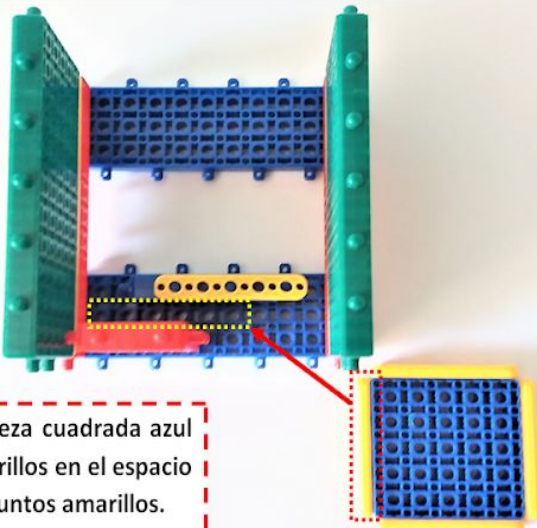
03



04

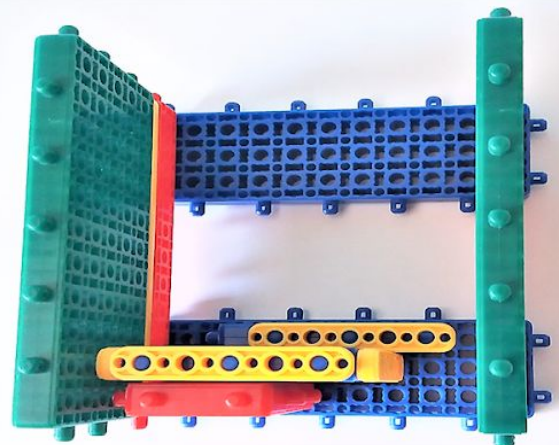


05



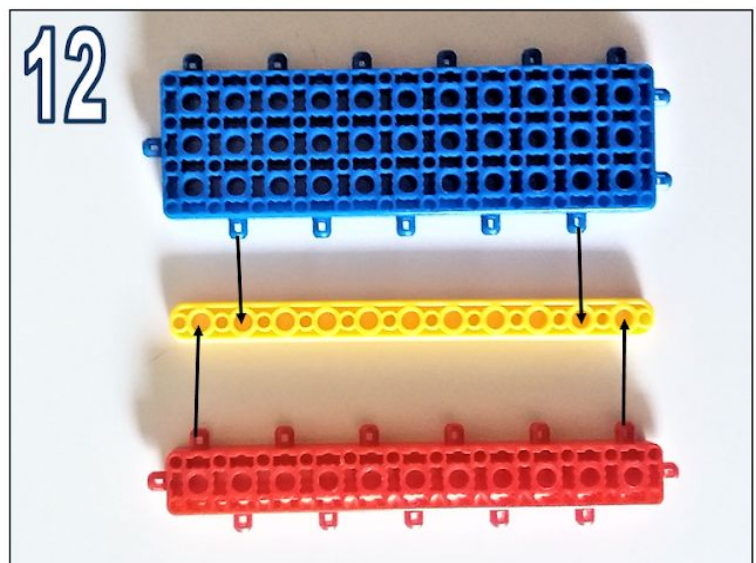
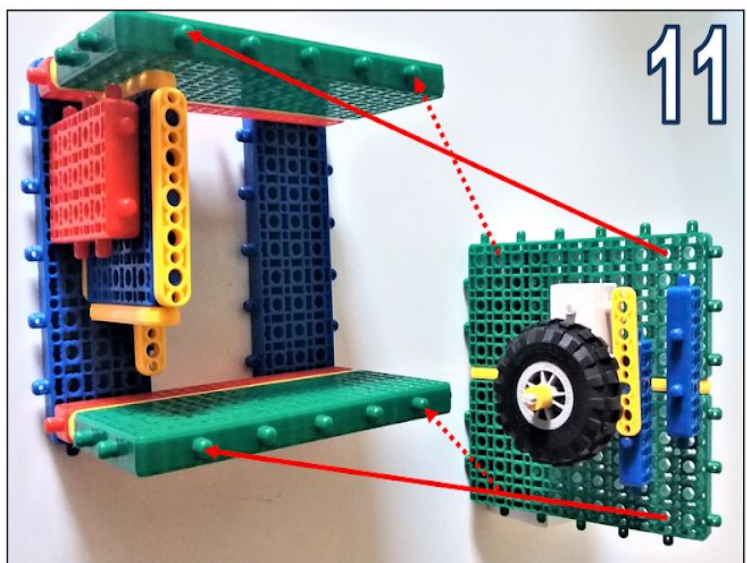
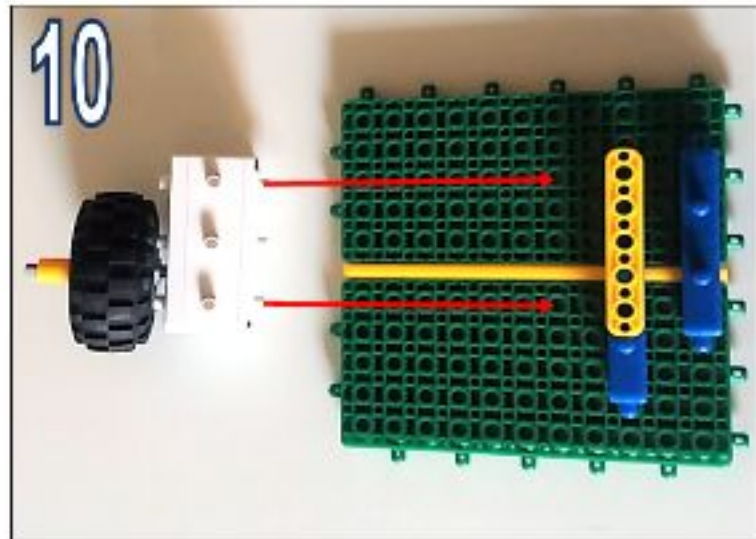
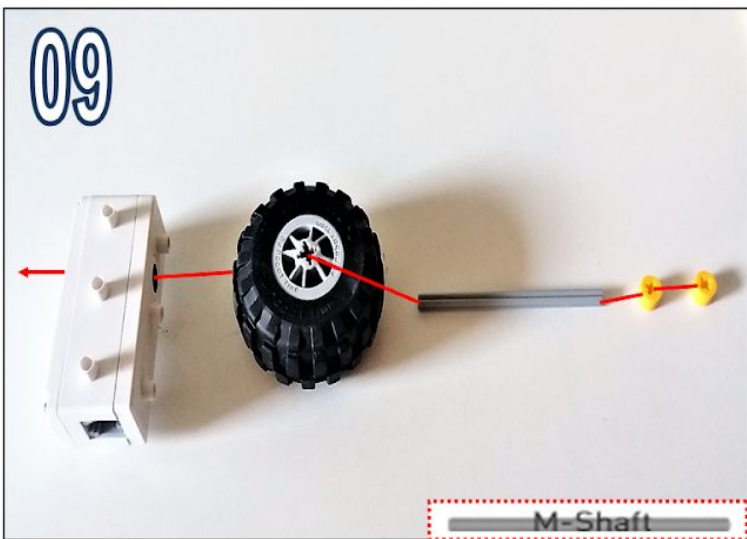
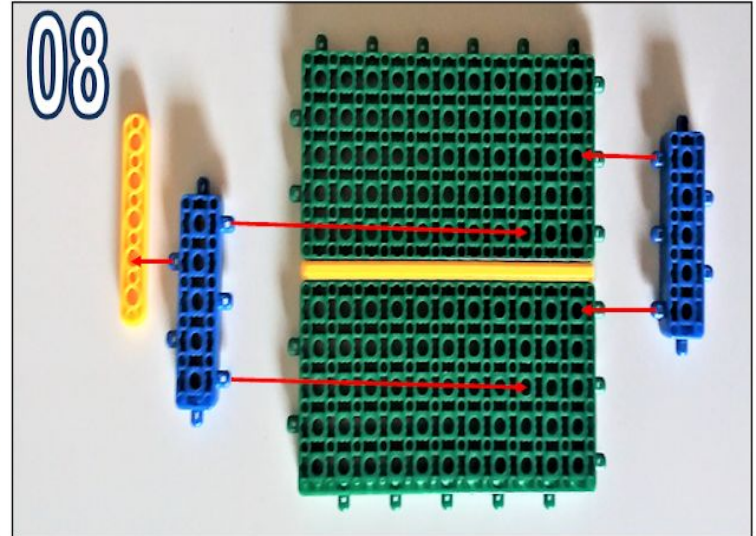
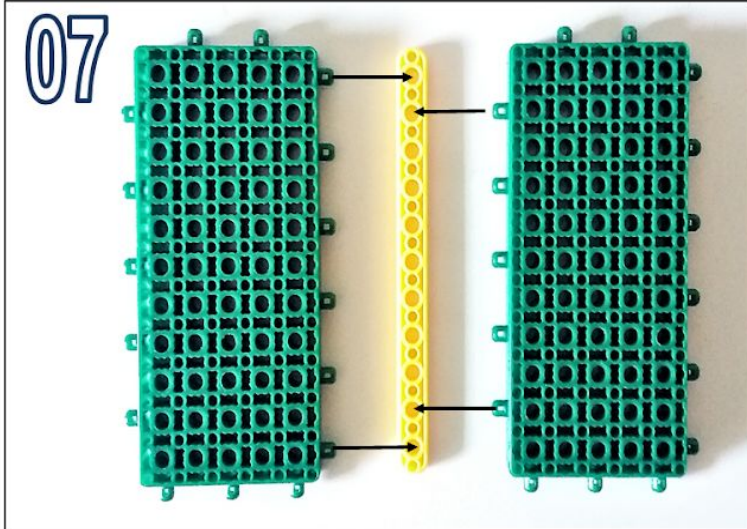
Introduce la pieza cuadrada azul de bordes amarillos en el espacio marcado con puntos amarillos.

06

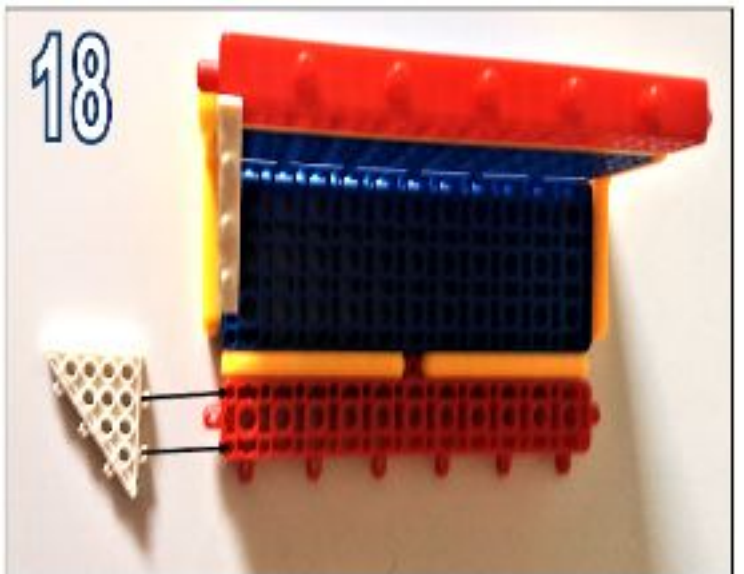
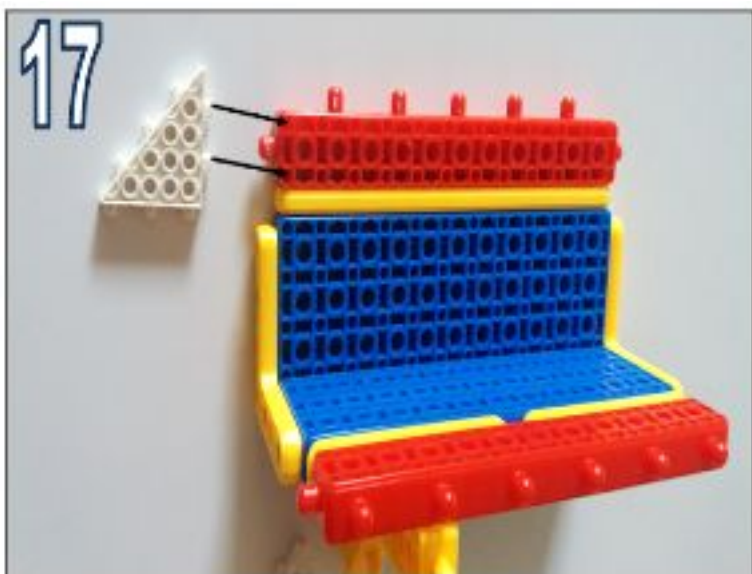
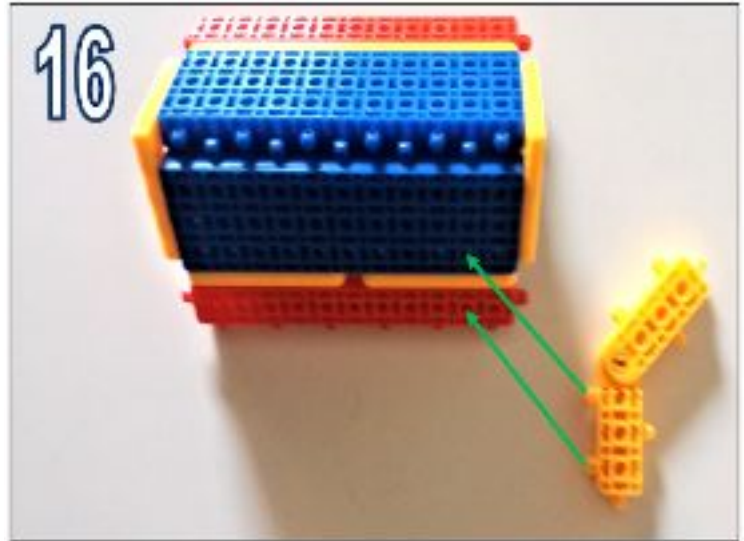
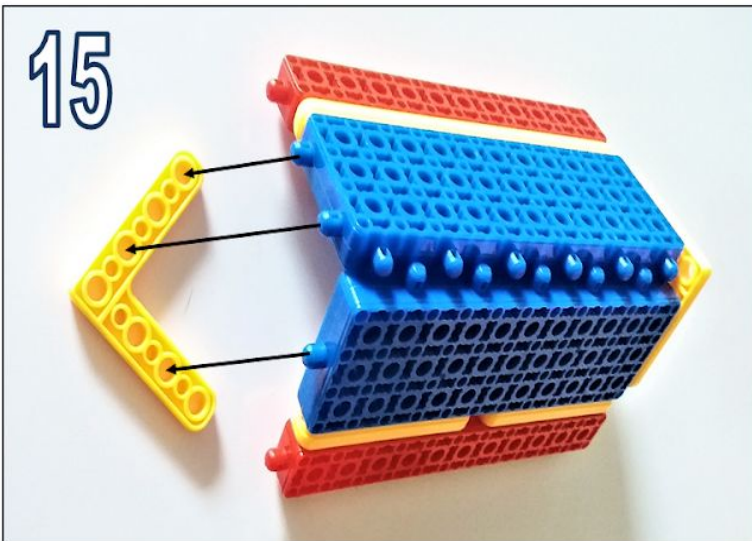
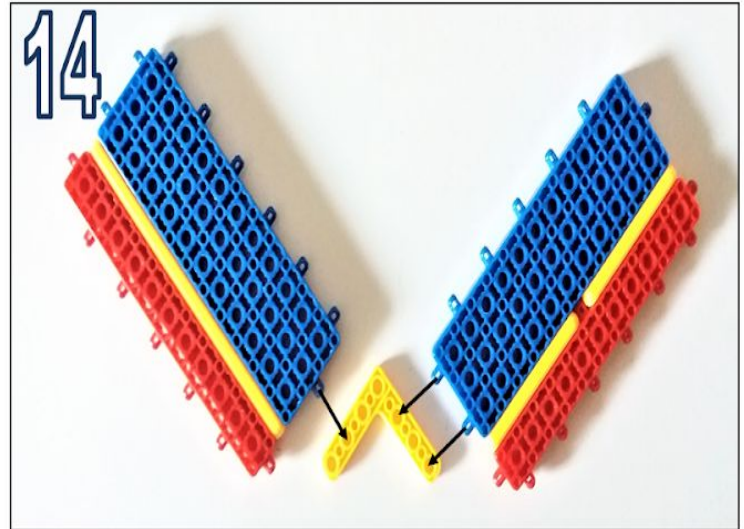
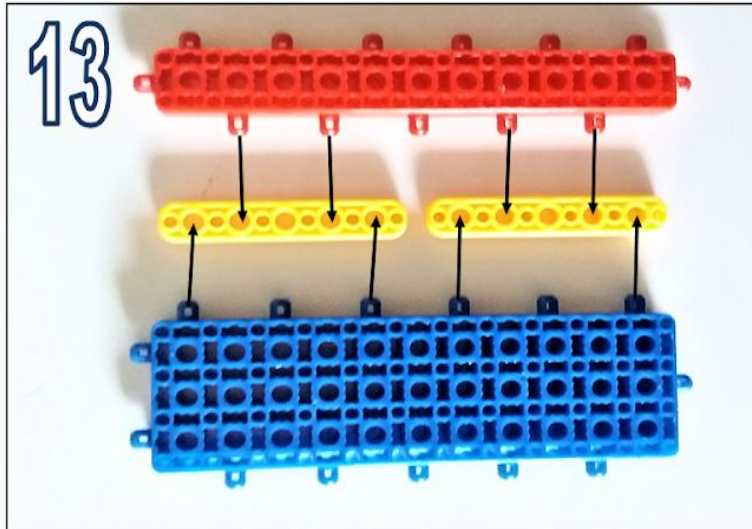


RESULTADO DEL PASO 05

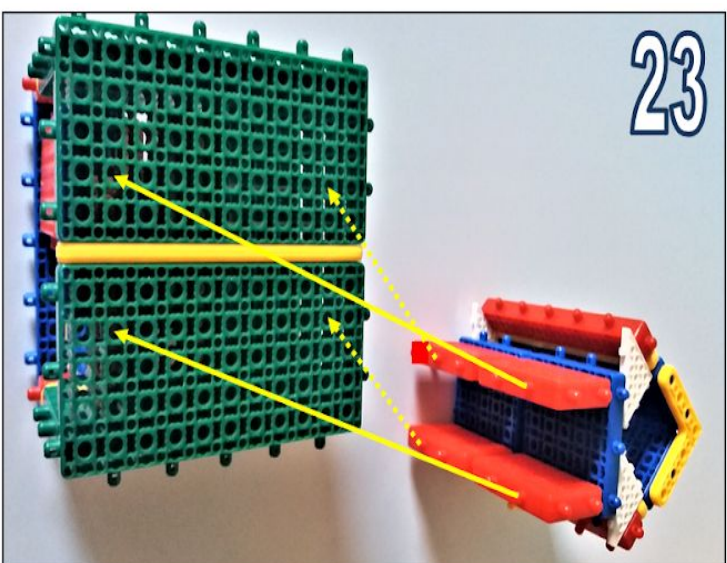
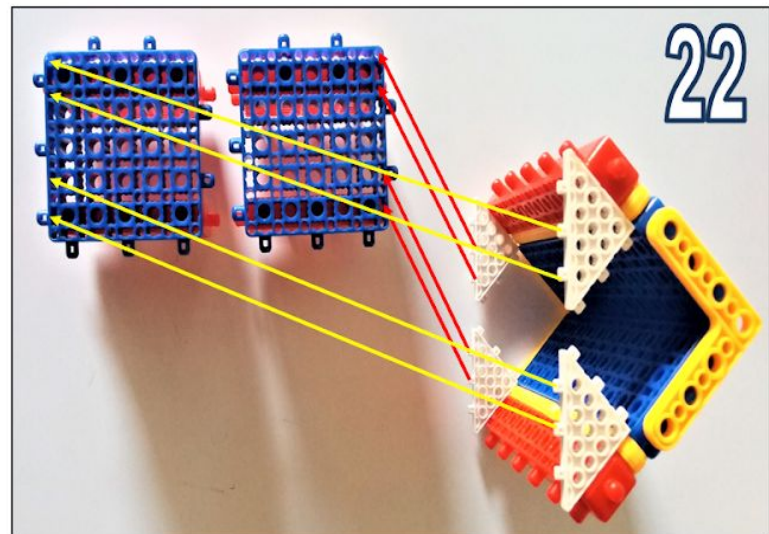
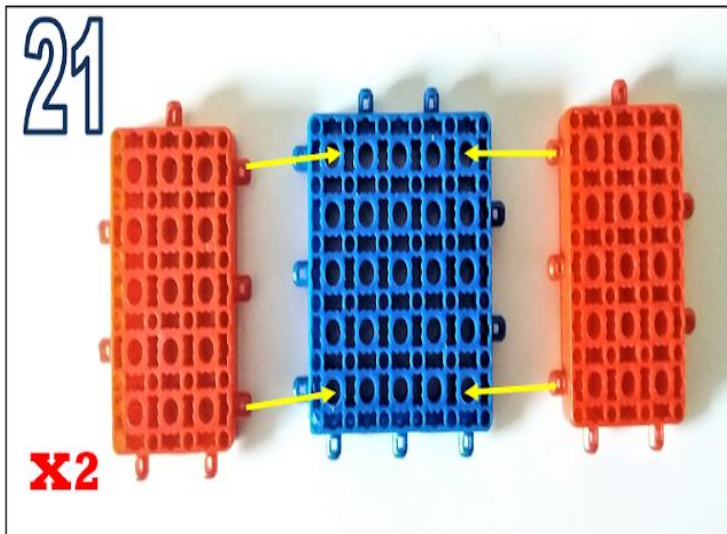
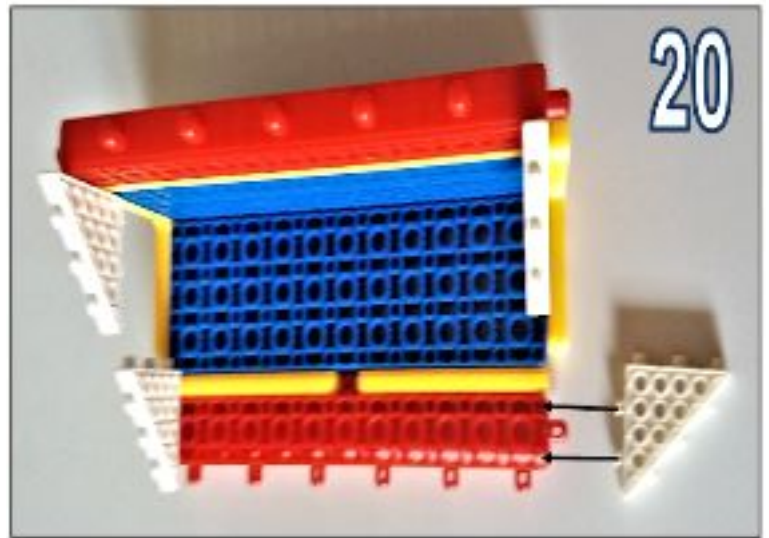




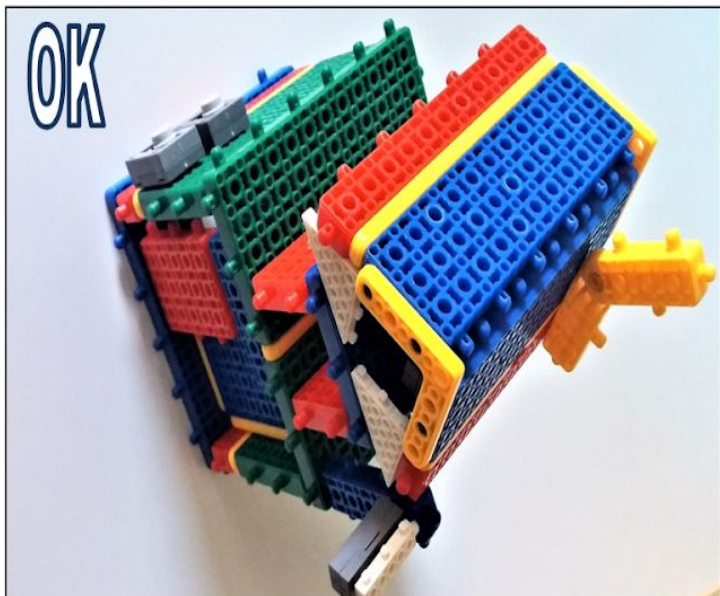
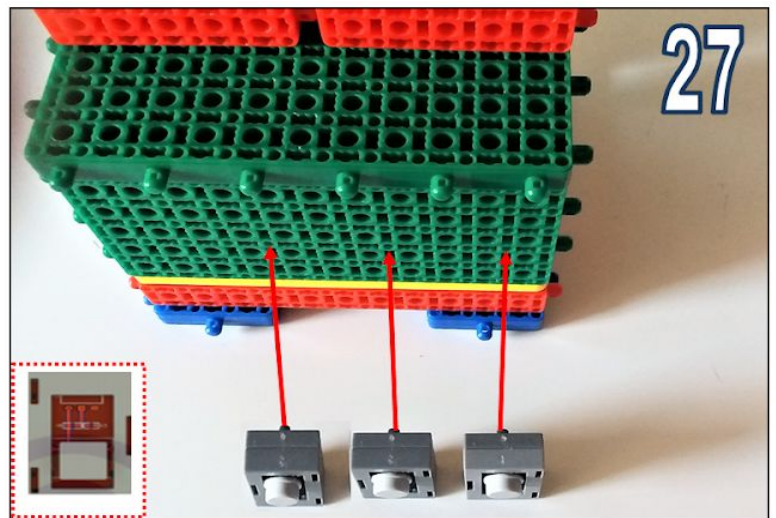
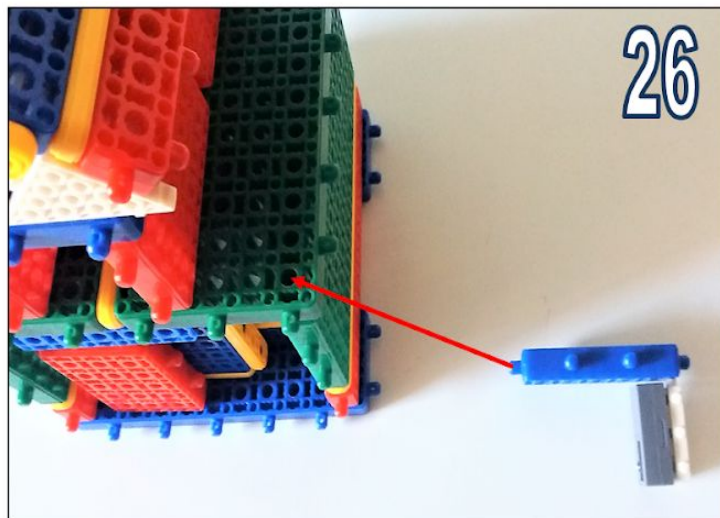
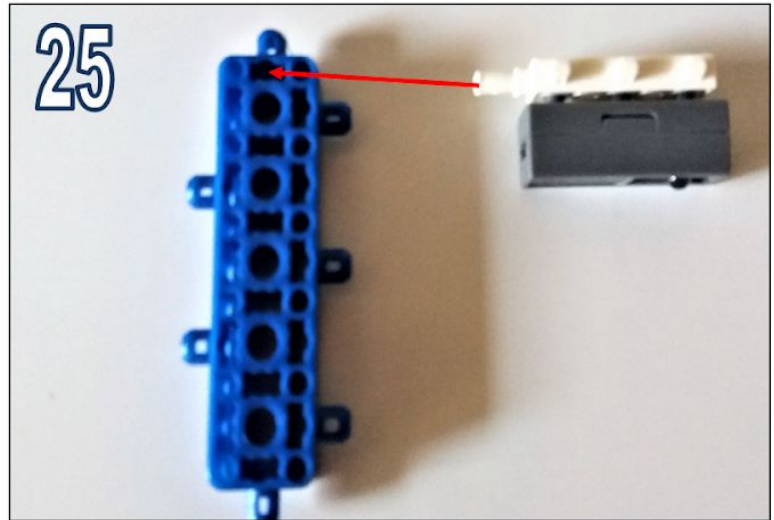
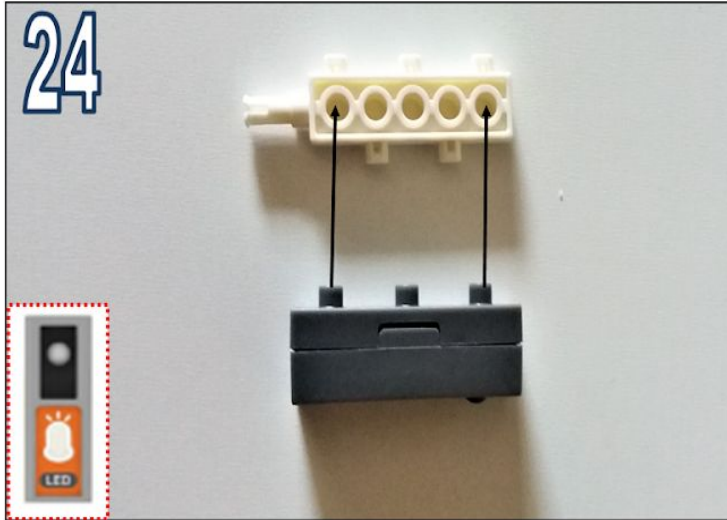












### Connect mainboard / touch sensor

① Connect card reader to connector D.



② Connect 3 pcs of touch sensors to connector A, B, C.



### Connect DC motor

① Connect 2 pcs of DC motors to connector 1,2.



② Connect 2 pcs of DC motors to connector 1  
Connect LED to connector



# Programación “Casa robótica”

